

University of Wollongong

Research Online

Faculty of Engineering and Information
Sciences - Papers: Part A

Faculty of Engineering and Information
Sciences

1-1-1998

Completeness of the propositions-as-types interpretation of intuitionistic logic into illative combinatory logic

Wil Dekkers

Catholic University, Netherlands

Martin Bunder

University of Wollongong, mbunder@uow.edu.au

Henk Barendregt

Catholic University, Netherlands

Follow this and additional works at: <https://ro.uow.edu.au/eispapers>



Part of the [Engineering Commons](#), and the [Science and Technology Studies Commons](#)

Research Online is the open access institutional repository for the University of Wollongong. For further information contact the UOW Library: research-pubs@uow.edu.au

Completeness of the propositions-as-types interpretation of intuitionistic logic into illative combinatory logic

Abstract

Illative combinatory logic consists of the theory of combinators or lambda calculus extended by extra constants (and corresponding axioms and rules) intended to capture inference. In a preceding paper, [2], we considered 4 systems of illative combinatory logic that are sound for first order intuitionistic propositional and predicate logic. The interpretation from ordinary logic into the illative systems can be done in two ways: following the propositions-as-types paradigm, in which derivations become combinators, or in a more direct way, in which derivations are not translated. Both translations are closely related in a canonical way. In the cited paper we proved completeness of the two direct translations. In the present paper we prove that also the two indirect translations are complete. These proofs are direct whereas in another version, [3], we proved completeness by showing that the two corresponding illative systems are conservative over the two systems for the direct translations. Moreover we shall prove that one of the systems is also complete for predicate calculus with higher type functions.

Keywords

into, illative, interpretation, combinatory, intuitionistic, types, propositions, completeness, logic

Disciplines

Engineering | Science and Technology Studies

Publication Details

Dekkers, W., Bunder, M. & Barendregt, H. (1998). Completeness of the propositions-as-types interpretation of intuitionistic logic into illative combinatory logic. *The Journal of Symbolic Logic*, 63 (3), 869-890.

COMPLETENESS OF THE PROPOSITIONS-AS-TYPES INTERPRETATION OF INTUITIONISTIC LOGIC INTO ILLATIVE COMBINATORY LOGIC

WIL DEKKERS, MARTIN BUNDER, AND HENK BARENDREGT

Abstract. Illative combinatory logic consists of the theory of combinators or lambda calculus extended by extra constants (and corresponding axioms and rules) intended to capture inference. In a preceding paper, [2], we considered 4 systems of illative combinatory logic that are sound for first order intuitionistic propositional and predicate logic. The interpretation from ordinary logic into the illative systems can be done in two ways: following the propositions-as-types paradigm, in which derivations become combinators, or in a more direct way, in which derivations are not translated. Both translations are closely related in a canonical way. In the cited paper we proved completeness of the two direct translations. In the present paper we prove that also the two indirect translations are complete. These proofs are direct whereas in another version, [3], we proved completeness by showing that the two corresponding illative systems are conservative over the two systems for the direct translations. Moreover we shall prove that one of the systems is also complete for predicate calculus with higher type functions.

§1. Introduction. In [2] we introduced 4 systems of illative combinatory logic (ICL). We derived roughly the following soundness result

$$\Delta \vdash_L A \Rightarrow [\Delta] \vdash_C [A],$$

where L represents propositional or predicate logic and $[-]$ one of two possible translations of each system into an ICL system C. Of the interpretations one is the propositions-as-types interpretation due to Curry, Howard and de Bruijn, the other is a more direct interpretation.

We derived completeness results for the direct translations of propositional and predicate calculus into 2 of the 4 systems of ICL. These, again roughly, took the following form

$$[\Delta] \vdash_C [A] \Rightarrow \Delta \vdash_L A.$$

In the present paper we shall prove that also the two indirect translations are complete. These completeness results imply the consistency of the ICL's involved. Moreover we shall prove that one of the systems is also complete for predicate calculus with higher type functions.

§2. Some definitions of preceding paper. This paper is a continuation of a preceding paper, [2], by the same authors. We will refer to that paper most of the time as B;

Received January 16, 1996; revised November 11, 1996.
Research supported by the Australian Research Council.

© 1998, Association for Symbolic Logic
0022-4812/98/6303-0007/\$3.20

so for example Definition B2.1 means Definition 2.1 in [2]. In this section we repeat some definitions of [2] that are needed in the present paper. For an introduction into ICL-systems, motivations, examples, propositions with proofs, and references we refer to [2].

DEFINITION 2.1 (Definition B2.1; the logic system PROP). PROP is the \supset fragment of intuitionistic propositional logic determined as follows.

(i) The set of formulas of PROP, notation \mathbb{F}_{PROP} , is defined by the following abstract syntax

$$\mathbb{F}_{\text{PROP}} = \mathbb{V} \mid \mathbb{F}_{\text{PROP}} \supset \mathbb{F}_{\text{PROP}}.$$

Here \mathbb{V} is a set of propositional variables.

(ii) Let $\Gamma \subseteq \mathbb{F}_{\text{PROP}}$ and $\varphi \in \mathbb{F}_{\text{PROP}}$. Then $\Gamma \vdash_{\text{PROP}} \varphi$ is defined by the following system of natural deduction.

PROP

$\begin{array}{lcl} \varphi \in \Gamma & \Rightarrow & \Gamma \vdash \varphi; \\ \Gamma \vdash \varphi \supset \psi, \Gamma \vdash \varphi & \Rightarrow & \Gamma \vdash \psi; \\ \Gamma, \varphi \vdash \psi & \Rightarrow & \Gamma \vdash \varphi \supset \psi. \end{array}$
--

DEFINITION 2.2 (Definition B2.2; the logic system PRED). PRED is the $\{\supset, \forall\}$ fragment of first order many-sorted intuitionistic predicate calculus of a given signature s .

Below as an example, we will treat a version of PRED with s the signature of the structure

$$\langle \mathbf{A}_1, \mathbf{A}_2, \mathbf{f}, \mathbf{g}, \mathbf{P}, \mathbf{a} \rangle$$

with

$$\begin{array}{ll} \mathbf{A}_1, \mathbf{A}_2 & \text{nonempty sets;} \\ \mathbf{f} : \mathbf{A}_1 \rightarrow \mathbf{A}_1 & \text{a unary function;} \\ \mathbf{g} : \mathbf{A}_1 \rightarrow \mathbf{A}_2 \rightarrow \mathbf{A}_1 & \text{a binary function;} \\ \mathbf{P} \subseteq \mathbf{A}_1 & \text{a unary relation;} \\ \mathbf{a} \in \mathbf{A}_1 & \text{a constant.} \end{array}$$

(All results also hold for arbitrary signatures.)

(i) The set of terms of PRED, notation \mathbb{T}_{PRED} , is defined by the following abstract syntax.

$$\begin{array}{l} \mathbb{T}_{\text{PRED}} = \mathbb{T}_{\mathbf{A}_1} \mid \mathbb{T}_{\mathbf{A}_2}; \\ \mathbb{T}_{\mathbf{A}_1} = \mathbb{V}^{\mathbf{A}_1} \mid \mathbf{a} \mid \mathbf{f} \mathbb{T}_{\mathbf{A}_1} \mid \mathbf{g} \mathbb{T}_{\mathbf{A}_1} \mathbb{T}_{\mathbf{A}_2}; \\ \mathbb{T}_{\mathbf{A}_2} = \mathbb{V}^{\mathbf{A}_2}. \end{array}$$

(ii) The set of formulas of PRED, notation \mathbb{F}_{PRED} , is defined by the following abstract syntax.

$$\mathbb{F}_{\text{PRED}} = \mathbf{P} \mathbb{T}_{\mathbf{A}_1} \mid \mathbb{F}_{\text{PRED}} \supset \mathbb{F}_{\text{PRED}} \mid \forall \mathbb{V}^{\mathbf{A}_1} \mathbb{F}_{\text{PRED}}.$$

(ii) $\Gamma \vdash_{\text{PRED}} \varphi$ is axiomatised by the following system of natural deduction.

PRED

$\varphi \in \Gamma \Rightarrow \Gamma \vdash \varphi;$
$\Gamma \vdash \varphi \supset \psi, \Gamma \vdash \varphi \Rightarrow \Gamma \vdash \psi;$
$\Gamma, \varphi \vdash \psi \Rightarrow \Gamma \vdash \varphi \supset \psi;$
$\Gamma \vdash \forall x^{A_i} \varphi, t \in \mathbb{T}_{A_i} \Rightarrow \Gamma \vdash \varphi[x^{A_i} := t];$
$\Gamma \vdash \varphi, x^{A_i} \notin \text{FV}(\Gamma) \Rightarrow \Gamma \vdash \forall x^{A_i} \varphi.$

The systems PROP and PRED are being interpreted in ICL's by two kinds of embeddings. The first kind is 'direct' and the second kind is according to the 'propositions-as-types' and 'proofs-as-terms' paradigm. As there are two logical systems, PROP and PRED, there are four systems of ICL. These systems are called $\mathcal{I}\mathbf{P}$, $\mathcal{I}\mathbf{\Xi}$, $\mathcal{I}\mathbf{F}$, and $\mathcal{I}\mathbf{G}$ respectively. Their use for the two kinds of interpretation is as follows. Let $[]^1$ be the direct, and $[]^2$ the propositions-as-types translation. Then the following table shows the systems of ICL that are used for the two translations of PROP and PRED.

	$[]^1$	$[]^2$
PROP	$\mathcal{I}\mathbf{P}$	$\mathcal{I}\mathbf{F}$
PRED	$\mathcal{I}\mathbf{\Xi}$	$\mathcal{I}\mathbf{G}$

For example

$$[]^2 : \text{PRED} \rightarrow \mathcal{I}\mathbf{G}.$$

Now we will describe the four systems of ICL.

DEFINITION 2.3 (Definition B2.3; the four systems of ICL). Let $\mathbf{T} = \Lambda(\mathbf{\Xi}, \mathbf{L})$, be the set of type-free lambda terms extended by the extra constants $\mathbf{\Xi}$ and \mathbf{L} .

(i) Define the following terms in \mathbf{T} .

$$\begin{aligned} \mathbf{P} &\equiv \lambda xy. \mathbf{\Xi}(\mathbf{K}x)(\mathbf{K}y), \\ \mathbf{F} &\equiv \lambda xyz. \mathbf{\Xi}x(y \circ z), \\ \mathbf{G} &\equiv \lambda xyz. \mathbf{\Xi}x(\mathbf{S}yz), \\ \mathbf{H} &\equiv \mathbf{L} \circ \mathbf{K}, \end{aligned}$$

where $\mathbf{K} \equiv \lambda pq. p$, $M \circ N \equiv \lambda x. M(Nx)$ and $\mathbf{S} \equiv \lambda pqr. pr(qr)$.

Write $X \supset Y$ for $\mathbf{P}XY$.

(ii) Define the following four systems of illative combinatory logic $\mathcal{I}\mathbf{P}$, $\mathcal{I}\mathbf{\Xi}$, $\mathcal{I}\mathbf{F}$ and $\mathcal{I}\mathbf{G}$. \mathbf{T} is the set of terms of all 4 systems. A basis Γ is a set of terms. All four systems have as rules the following:

All systems

$X \in \Gamma \Rightarrow \Gamma \vdash X;$
$\Gamma \vdash X, X =_{\beta\eta} Y \Rightarrow \Gamma \vdash Y.$

The four systems have the following specific rules:

\mathcal{JP}

P_e	$\Gamma \vdash X \supset Y, \Gamma \vdash X \Rightarrow \Gamma \vdash Y;$
P_i	$\Gamma, X \vdash Y, \Gamma \vdash \mathbf{H}X \Rightarrow \Gamma \vdash X \supset Y;$
P_H	$\Gamma, X \vdash \mathbf{H}Y, \Gamma \vdash \mathbf{H}X \Rightarrow \Gamma \vdash \mathbf{H}(X \supset Y).$

$\mathcal{J}\Xi$

Ξ_e	$\Gamma \vdash \Xi XY, \Gamma \vdash XV \Rightarrow \Gamma \vdash YV;$
Ξ_i	$\Gamma, Xx \vdash Yx, \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y) \Rightarrow \Gamma \vdash \Xi XY;$
Ξ_H	$\Gamma, Xx \vdash \mathbf{H}(Yx), \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y) \Rightarrow \Gamma \vdash \mathbf{H}(\Xi XY).$

\mathcal{JF}

F_e	$\Gamma \vdash \mathbf{F}XYZ, \Gamma \vdash XV \Rightarrow \Gamma \vdash Y(ZV);$
F_i	$\Gamma, Xx \vdash Y(Zx), \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y, Z) \Rightarrow \Gamma \vdash \mathbf{F}XYZ;$
F_L	$\Gamma, Xx \vdash \mathbf{L}Y, \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y) \Rightarrow \Gamma \vdash \mathbf{L}(\mathbf{F}XY).$

\mathcal{JG}

G_e	$\Gamma \vdash \mathbf{G}XYZ, \Gamma \vdash XV \Rightarrow \Gamma \vdash YV(ZV);$
G_i	$\Gamma, Xx \vdash Yx(Zx), \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y, Z) \Rightarrow \Gamma \vdash \mathbf{G}XYZ;$
G_L	$\Gamma, Xx \vdash \mathbf{L}(Yx), \Gamma \vdash \mathbf{L}X, x \notin \text{FV}(\Gamma, X, Y) \Rightarrow \Gamma \vdash \mathbf{L}(\mathbf{G}XY).$

DEFINITION 2.4 (Definition B2.8; interpretation of PROP). Let r be a closed term in $\Lambda(\Xi, \mathbf{L})$. Two maps (for $i = 1, 2$)

$$[-]_r^i : \mathbb{F}_{\text{PROP}} \rightarrow \Lambda(\Xi, \mathbf{L})$$

and two maps

$$\Gamma_r^i : \mathbb{F}_{\text{PROP}} \rightarrow \text{illative contexts}$$

are defined by the following table. (Note that these illative contexts are effectively grammatical conditions on the variables (propositional, individual) that appear in a proposition.)

φ	$[\varphi]_r^1$	$\Gamma_r^1(\varphi)$	$[\varphi]_r^2$	$\Gamma_r^2(\varphi)$
p	rp	$\mathbf{H}(rp)$	rp	$\mathbf{L}(rp)$
$\psi \supset \chi$	$[\psi]_r^1 \supset [\chi]_r^1$	$\Gamma_r^1(\psi), \Gamma_r^1(\chi)$	$\mathbf{F}[\psi]_r^2[\chi]_r^2$	$\Gamma_r^2(\psi), \Gamma_r^2(\chi)$

REMARK 2.5. The r in the above can be replaced by \mathbf{I} (i.e., omitted). In other versions of this paper however we specialised to $r = \mathbf{K}$. (cf., Remark 7.1.) Moreover in Proposition B2.15 we used it to derive a relation between the two interpretations.

DEFINITION 2.6 (Definition B2.12; interpretation of PRED).

(i) $\Lambda^s(\Xi, \mathbf{L})$ is $\Lambda(\Xi, \mathbf{L})$ extended by the extra constants A_1, A_2, P, f, g, a associated with the signature s of the manysorted structure of our example. Because we are going to interpret many sorted predicate logic with sorts $\mathbf{A}_1, \mathbf{A}_2$, it is useful to have among the free variables of the λ -calculus infinite sets $\mathcal{V}_1, \mathcal{V}_2$, with $\mathcal{V}_i = \{x_i, y_i, z_i, \dots\}$. x, y, z denote arbitrary variables.

(ii) Let r be a closed term in $\Lambda^s(\Xi, \mathbf{L})$. Two maps (for $i = 1, 2$)

$$[-]_r^i : \mathbb{F}_{\text{PRED}} \rightarrow \Lambda^s(\Xi, \mathbf{L})$$

and a map

$$\Gamma : \mathbb{F}_{\text{PRED}} \rightarrow \text{illative contexts}$$

are defined by the following tables:

t	$[t]_r^i$	$\Gamma(t)$
$x^{\mathbf{A}_i}$	x_j	$A_j x_j$
\mathbf{a}	a	\emptyset
$\mathbf{f} s$	$f[s]_r^i$	$\Gamma(s)$
$\mathbf{g} s t$	$g[s]_r^i[t]_r^i$	$\Gamma(s), \Gamma(t)$

φ	$[\varphi]_r^1$	$[\varphi]_r^2$	$\Gamma(\varphi)$
$\mathbf{P} t$	$r(P[t]_r^1)$	$r(P[t]_r^2)$	$\Gamma(t)$
$\psi \supset \chi$	$[\psi]_r^1 \supset [\chi]_r^1$	$\mathbf{F}[\psi]_r^2[\chi]_r^2$	$\Gamma(\psi), \Gamma(\chi)$
$\forall x^{\mathbf{A}_i} \psi$	$\Xi A_i(\lambda x_i. [\psi]_r^1)$	$\mathbf{G} A_i(\lambda x_i. [\psi]_r^2)$	$\Gamma(\psi) - \{A_i x_i\}$

(iii)

$$\Gamma_{r,s}^1 = \langle \mathbf{L} A_1, \mathbf{L} A_2, \mathbf{F} A_1 A_1 f, \mathbf{F} A_1 (\mathbf{F} A_2 A_1) g, \mathbf{F} A_1 \mathbf{H}(r \circ P), A_1 a \rangle,$$

$$\Gamma_{r,s}^2 = \langle \mathbf{L} A_1, \mathbf{L} A_2, \mathbf{F} A_1 A_1 f, \mathbf{F} A_1 (\mathbf{F} A_2 A_1) g, \mathbf{F} A_1 \mathbf{L}(r \circ P), A_1 a \rangle$$

and

$$\Gamma_{r,s}^{i,+} = \Gamma_{r,s}^i \cup \{A_2 x_2\} \text{ where } x_2 \in \mathcal{V}_2 \text{ is some variable.}$$

The definitions $\Gamma_{r,s}^i$ and $\Gamma_{r,s}^{i,+}$ of course refer to our example of a many-sorted predicate calculus with signature s .

§3. Summary of results in preceding and present paper. We had as aim in the preceding paper to prove

- (i) $\Delta \vdash_{\text{PROP}} \varphi \Leftrightarrow \forall \text{ closed } r[\dots, [\Delta]_r^1 \vdash_{\mathcal{S}\text{P}} [\varphi]_r^1];$
- (ii) $\Delta \vdash_{\text{PRED}} \varphi \Leftrightarrow \forall \text{ closed } r[\dots, [\Delta]_r^1 \vdash_{\mathcal{S}\Xi} [\varphi]_r^1];$
- (iii) $\Delta \vdash_{\text{PROP}} \varphi \Leftrightarrow \forall \text{ closed } r \exists M[\dots, [\Delta]_r^2 \vdash_{\mathcal{S}\text{F}} [\varphi]_r^2 M];$
- (iv) $\Delta \vdash_{\text{PRED}} \varphi \Leftrightarrow \forall \text{ closed } r \exists M[\dots, [\Delta]_r^2 \vdash_{\mathcal{S}\text{G}} [\varphi]_r^2 M];$

where \dots_i stands for $\Gamma_r^i(\Delta, \varphi)$ in the cases of PROP and for $\Gamma_{r,s}^{i,+}, \Gamma(\Delta, \varphi)$ in the cases of PRED.

The proofs of soundness (\Rightarrow) were easy. (cf., Propositions B2.11 and B2.14). In Propositions B3.14 and B3.11 we proved completeness for the 2 direct translations $[]^1 : \text{PROP} \rightarrow \mathcal{S}\mathbf{P}$ and $[]^1 : \text{PRED} \rightarrow \mathcal{S}\Xi$, ((i) \Leftarrow and (ii) \Leftarrow), by specialising

to $r = \mathbf{I}$. In the present paper we prove completeness for the 2 indirect translations $[]^2 : \text{PROP} \rightarrow \mathcal{S}\mathbf{F}$ and $[]^2 : \text{PRED} \rightarrow \mathcal{S}\mathbf{G}$, ((iii) \Leftarrow and (iv) \Leftarrow), also by specialising to $r = \mathbf{I}$. In Section 7 we point out that completeness for all 4 cases can be proved also by specialising to $r = \mathbf{K}$.

The completeness proof for the direct translation $[]^1 : \text{PRED} \rightarrow \mathcal{S}\Xi$ ((ii) \Leftarrow) was given in the following way. We had to show

$$\Gamma_s^{1,+}, [\Delta]^1, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\Xi} [\varphi]^1 \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

(cf., page B781.) Write $\Gamma' = \Gamma_s^{1,+}, [\Delta]^1, \Gamma(\Delta, \varphi)$. First we defined in B3.2 a set \mathcal{O} in order to analyze the terms M such that $\Gamma' \vdash_{\mathcal{S}\Xi} M$. We defined $\overline{\mathcal{O}} = \{M \mid \exists N \in \mathcal{O} \mid N =_{\beta\eta} M\}$ and it was clear that $\Gamma' \subseteq \overline{\mathcal{O}}$. We showed in Proposition B3.10 that \mathcal{O} is an invariant (modulo $\beta\eta$ -equality) for derivations in $\mathcal{S}\Xi$:

$$\Gamma \vdash_{\mathcal{S}\Xi} M, \Gamma \subseteq \overline{\mathcal{O}} \Rightarrow M \in \overline{\mathcal{O}}.$$

Using this result we then proved in Proposition B3.11

$$\Gamma' \vdash_{\mathcal{S}\Xi} [\varphi]^1 \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

The completeness proof for $[]^1 : \text{PROP} \rightarrow \mathcal{S}\mathbf{P}$ ((i) \Leftarrow) was done in a similar but easier way.

In the present paper we will prove completeness of $[]^2 : \text{PROP} \rightarrow \mathcal{S}\mathbf{F}$ and $[]^2 : \text{PRED} \rightarrow \mathcal{S}\mathbf{G}$ ((iii) \Leftarrow and (iv) \Leftarrow).

We start with the most difficult case, the proof of completeness of $[]^2 : \text{PRED} \rightarrow \mathcal{S}\mathbf{G}$. We define in Definition 4.2 a set \mathcal{O}_G and we will show in Proposition 4.10 that \mathcal{O}_G is an invariant (modulo $\beta\eta$ -equality) for derivations in $\mathcal{S}\mathbf{G}$:

$$\Gamma \vdash_{\mathcal{S}\mathbf{G}} M, \Gamma \subseteq \overline{\mathcal{O}_G} \Rightarrow M \in \overline{\mathcal{O}_G}.$$

The invariant \mathcal{O}_G is more complicated than \mathcal{O} of B3.2 and we cannot use it to prove completeness directly in a way similar to the proof of completeness for $\mathcal{S}\Xi$ relative to PRED by means of \mathcal{O} in B3.11. In fact we shall use \mathcal{O}_G in order to show in Lemma 4.18 that in a proof of $\Gamma \vdash_{\mathcal{S}\mathbf{G}} M$, where $\Gamma \subseteq \overline{\mathcal{O}_G}$, all cut formulas can be eliminated. Then we define in Definition 4.21 a second invariant \mathcal{O}_1 . This \mathcal{O}_1 plays a role similar to that of \mathcal{O} in B3.2. Using this invariant we prove in 4.22–4.25 the completeness in a way similar to the proof of completeness of $[]^1 : \text{PRED} \rightarrow \mathcal{S}\Xi$ in B3.2–B3.11.

Completeness of $\mathcal{S}\mathbf{F}$ for PROP is easier. There is no need for cut elimination and we give the proof directly, using an invariant \mathcal{O}_2 similar to \mathcal{O} and \mathcal{O}_1 .

In the last part of the paper we shall introduce another logic system: Predicate Calculus with Higher Type Functions, notation $\text{PRED}\lambda\rightarrow$. We shall prove in Proposition 6.12 that $\mathcal{S}\mathbf{G}$ is also complete for $\text{PRED}\lambda\rightarrow$ under the second translation $[]^2$.

§4. Completeness of $\mathcal{S}\mathbf{G}$ for PRED. We will show for $\varphi \in \mathbb{F}_{\text{PRED}}$, $\Delta \subseteq \mathbb{F}_{\text{PRED}}$:

$$\forall \text{ closed } r \exists M [\Gamma_{r,s}^{2,+}, [\Delta]_r^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]_r^2 M] \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

It is sufficient to show

$$\Gamma_{1,s}^{2,+}, [\Delta]_1^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]_1^2 M \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

We omit the index **I** in the notation and we prove

$$\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{J}\mathbf{G}} [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

The proof is again in several steps. First we define in Definition 4.2 an *invariant* \mathcal{O}_G (modulo $\beta\eta$ -equality) for derivations in $\mathcal{J}\mathbf{G}$. Using this invariant we show in Lemma 4.18 that in a proof of $\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{J}\mathbf{G}} N$ all cuts can be eliminated. Then we define in Definition 4.21 a second invariant \mathcal{O}_1 , similar to \mathcal{O} in B3.2 and using this invariant we prove in 4.22 - 4.25 the completeness in a way similar to the proof of completeness of $[\]^1 : \text{PRED} \rightarrow \mathcal{J}\Xi$ in B3.2 - B3.11. Instead of $\vdash_{\mathcal{J}\mathbf{G}}$ we shall mostly write \vdash .

Now we repeat Definition B3.2 of the invariant \mathcal{O} for derivations in $\mathcal{J}\Xi$ for the manysorted structure of our example, in order to contrast it with the one for derivations in $\mathcal{J}\mathbf{G}$ of Definition 4.2 and also because we shall refer to it often in the sequel. Instead of x_i, \mathcal{V}_i and \mathcal{T}_i we shall write $x^{A_i}, \mathcal{V}^{A_i}$ and \mathcal{T}^{A_i} .

DEFINITION 4.1 (Invariant for derivations in $\mathcal{J}\Xi$).

$$\begin{aligned} \mathcal{T} &\equiv \mathcal{T}^{A_1} \mid \mathcal{T}^{A_2}; \\ \mathcal{T}^{A_1} &\equiv \mathcal{V}^{A_1} \mid a \mid f \mathcal{T}^{A_1} \mid g \mathcal{T}^{A_1} \mathcal{T}^{A_2}; \\ \mathcal{T}^{A_2} &\equiv \mathcal{V}^{A_2}; \\ \mathcal{P} &\equiv P \mathcal{T}^{A_1} \mid \Xi A_i (\lambda x^{A_i}. \mathcal{P}) \mid \Xi (\mathbf{K} \mathcal{P}) (\mathbf{K} \mathcal{P}); \\ \mathcal{G} &\equiv \mathbf{L} A_i \mid A_i \mathcal{T}^{A_i} \mid \Xi A_i (\lambda x^{A_i}. \mathcal{G}) \mid \Xi (\mathbf{K} \mathcal{P}) (\mathbf{K} \mathcal{G}) \mid \mathbf{L} (\mathbf{K} \mathcal{P}); \\ \mathcal{O} &\equiv \mathcal{G} \mid \mathcal{P}. \end{aligned}$$

Now we will define the invariant \mathcal{O}_G for derivations in $\mathcal{J}\mathbf{G}$. \mathcal{O}_G is more complicated than the invariant \mathcal{O} for $\mathcal{J}\Xi$ for several reasons. If $\Gamma_s^{1,+}, [\Delta]^1, \Gamma(\Delta, \varphi) \vdash \mathbf{L} X$ in system $\mathcal{J}\Xi$ then $X = A_i$ or $X = \mathbf{K} p$ with $p \in \mathcal{P}$. But if $\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash \mathbf{L} X$ in system $\mathcal{J}\mathbf{G}$ then we can have for example $X = \mathbf{F} A_1 A_2$ or even $X = \mathbf{F} p A_2$. Therefore we define an extension \mathcal{L}_G of the set of sorts $\{A_1, A_2\}$ containing these X 's. We need for each $l \in \mathcal{L}_G$ a set of variables \mathcal{V}_G^l , similar to the sets \mathcal{V}^{A_1} and \mathcal{V}^{A_2} . If we took a different set of variables for each $l \in \mathcal{L}_G$, then the Substitution Lemma 4.6, that is needed in the Proof of Proposition 4.10, would not hold. Therefore we define for each $l \in \mathcal{L}_G$ the skeleton $sk(l)$, such that $sk(p)$ is the same for all $p \in \mathcal{P}_G$ and we define $\mathcal{V}_G^{l_1} = \mathcal{V}_G^{l_2}$ iff $sk(l_1) = sk(l_2)$.

The sets \mathcal{T}_G^l will contain λ -abstractions: if $l \equiv \mathbf{F} l_1 l_2$ and $t^{l_2} \in \mathcal{T}_G^{l_2}$ then $\lambda x^{l_1}. t^{l_2} \in \mathcal{T}_G^l$. This may seem a little bit strange, but in fact it is very natural. For example we have $\vdash \mathbf{F} A_1 A_1 (\lambda x^{A_1}. x^{A_1})$ by rule \mathbf{F}_i . Hence $\lambda x^{A_1}. x^{A_1}$ should be in $\mathcal{T}_G^{\mathbf{F} A_1 A_1}$. Moreover in the Proof of Lemma 4.9 we really need that $\lambda x^{l_1}. t^{l_2} \in \mathcal{T}_G^{\mathbf{F} l_1 l_2}$.

Finally we had $\Xi(\mathbf{K} p)(\mathbf{K} O) \in \mathcal{O}$ whereas now we have $\Xi p(\lambda x^p. O) \in \mathcal{O}_G$, where x^p may occur free in O .

DEFINITION 4.2 (Invariant \mathcal{O}_G for derivations in $\mathcal{J}\mathbf{G}$). (i) $\Lambda^s(\Xi, \mathbf{L})$ is, as in Definition B2.12, $\Lambda(\Xi, \mathbf{L})$ extended by the extra constants A_1, A_2, P, f, g, a associated with the signature s of the manysorted structure of our example.

(ii) Now we will define simultaneously a set \mathcal{L}_G of sorts (an extension of the set $\{A_1, A_2\}$), for each $l \in \mathcal{L}_G$ the skeleton $sk(l)$, a set of variables \mathcal{V}_G^l and a set of terms \mathcal{T}_G^l , sets $\mathcal{P}_G, \mathcal{H}_G, \mathcal{G}_G$ and \mathcal{O}_G .

Definition of \mathcal{L}_G .

$$\mathcal{L}_G \equiv A_1 \mid A_2 \mid Pt^{A_1} \mid \mathbf{G}l_1(\lambda x^{l_1}.l_2) \quad (t^{A_1} \in \mathcal{T}_G^{A_1}, l_1, l_2 \in \mathcal{L}_G, x^{l_1} \in \mathcal{V}_G^{l_1}).$$

Definition of $sk(l)$.

$$\begin{aligned} sk(A_i) &\equiv A_i; \\ sk(Pt^{A_1}) &\equiv Px^{A_1} \quad (\text{i.e., } sk(Pt^{A_1}) \text{ is independent of } t^{A_1}); \\ sk(\mathbf{G}l_1(\lambda x^{l_1}.l_2)) &\equiv \mathbf{G}(sk(l_1))(\lambda x^{l_1}.sk(l_2)). \end{aligned}$$

Definition of \mathcal{V}_G^l .

We assume that for each skeleton $sk(l)$ there is a set of variables

$$\mathcal{V}_G^{sk(l)} \equiv \{x^{sk(l)}, x_1^{sk(l)}, x_2^{sk(l)}, \dots, y^{sk(l)}, y_1^{sk(l)}, y_2^{sk(l)}, \dots\}$$

such that $\mathcal{V}_G^{sk(l_1)} \cap \mathcal{V}_G^{sk(l_2)} = \emptyset$ if $sk(l_1) \neq sk(l_2)$, and for each $l \in \mathcal{L}_G$ we define

$$\mathcal{V}_G^l \equiv \mathcal{V}_G^{sk(l)}, \quad x^l \equiv x^{sk(l)}, x_i^l \equiv x_i^{sk(l)}, \quad y^l \equiv y^{sk(l)}, y_i^l \equiv y_i^{sk(l)}.$$

Definition of \mathcal{T}_G^l .

$$\begin{aligned} \mathcal{T}_G^l &\equiv a \mid \mathcal{V}_G^l \mid \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_G^{l_1}, & \text{if } l \equiv A_1; \\ \mathcal{T}_G^l &\equiv \mathcal{V}_G^l \mid \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_G^{l_1}, & \text{if } l \equiv A_2 \text{ or } l \equiv Pt^{A_1}; \\ \mathcal{T}_G^l &\equiv f \mid \mathcal{V}_G^l \mid \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_G^{l_1} \mid \lambda x^{A_1}. \mathcal{T}_G^{A_1}, & \text{if } l \equiv \mathbf{F}A_1A_1; \\ \mathcal{T}_G^l &\equiv g \mid \mathcal{V}_G^l \mid \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_G^{l_1} \mid \lambda x^{A_1}. \mathcal{T}_G^{\mathbf{F}A_2A_1}, & \text{if } l \equiv \mathbf{F}A_1(\mathbf{F}A_2A_1); \\ \mathcal{T}_G^l &\equiv \mathcal{V}_G^l \mid \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_G^{l_1} \mid \lambda x^{l_2}. \mathcal{T}_G^{l_3}, & \text{if } l \equiv \mathbf{G}l_2(\lambda x^{l_2}.l_3), \\ & & l \notin \{\mathbf{F}A_1A_1, \mathbf{F}A_1(\mathbf{F}A_2A_1)\}. \end{aligned}$$

Definition of $\mathcal{P}_G, \mathcal{H}_G, \mathcal{G}_G$ and \mathcal{O}_G .

$$\begin{aligned} \mathcal{P}_G &\equiv P\mathcal{T}_G^{A_1} \mid \mathbf{G}l(\lambda x^l. \mathcal{P}_G); \\ \mathcal{H}_G &\equiv (Pt^{A_1})t^{Pt^{A_1}} \mid \exists l(\lambda x^l. \mathcal{H}_G); \\ \mathcal{G}_G &\equiv \mathbf{L}\mathcal{L}_G \mid A_i \mathcal{T}_G^{A_i} \mid \exists l(\lambda x^l. \mathcal{G}_G); \\ \mathcal{O}_G &\equiv \mathcal{H}_G \mid \mathcal{G}_G. \end{aligned}$$

(iii) *Notation.*

$$\begin{aligned} l, l_1, l_2, l', \dots &\text{ denote elements of } \mathcal{L}_G; \\ p, p_1, p_2, p', \dots &\text{ denote elements of } \mathcal{P}_G. \end{aligned}$$

REMARKS 4.3. (i) If $\text{FV}(l_2) = \emptyset$ then $\mathbf{G}l_1(\lambda x^{l_1}.l_2) =_{\beta} \mathbf{F}l_1l_2$. In that case we will denote $\mathbf{G}l_1(\lambda x^{l_1}.l_2)$ usually by $\mathbf{F}l_1l_2$. In fact we did that already in the above definition.

(ii) The grammar in the definition of \mathcal{O}_G is not context-free and this causes some inaccuracies in the notation. In the definition of \mathcal{P}_G (and similarly at some other places) instead of $\mathbf{G}l(\lambda x^l. \mathcal{P}_G)$ we should write $\mathbf{G}\mathcal{L}_G(\lambda x^{\mathcal{L}_G}. \mathcal{P}_G)$, but then we do not know that these two \mathcal{L}_G 's represent the *same* $l \in \mathcal{L}_G$. (We may not have $\mathbf{G}l_1(\lambda x^{l_2}. \mathcal{P}_G)$.)

(iii) In the definition of \mathcal{T}_G^l instead of the clause $\mathcal{T}_G^{\mathbf{Gl}(\lambda x^l.l)} \mathcal{T}_G^{l_1}$ one might expect, in view of rule G_e a clause $t_1^{\mathbf{Gl}(\lambda x^l.l')} t_2^{l_1}$ where $l = l'[x^l := t_2^{l_1}]$, but that does not make a difference because we have for $l \in \mathcal{L}_G$

$$\mathcal{T}_G^{l[x^l := t^{l_1}]} = \mathcal{T}_G^l,$$

as follows easily from

$$\mathcal{V}_G^{l[x^l := t^{l_1}]} = \mathcal{V}_G^l$$

in Lemma 4.6.

- LEMMA 4.4. (i) $\exists l(\lambda x^l.pt) = \mathbf{Gl}(\lambda x^l.p)(\lambda x^l.t)$;
(ii) $\mathbf{Gl}(\lambda x^l.p)t = \exists l(\lambda x^l.p(tx^l))$, $x^l \notin \text{FV}(t)$;
(iii) $\exists l(\lambda x^l.pt^p) = \mathbf{Gl}(\lambda x^l.p)t^{\mathbf{Gl}(\lambda x^l.p)}$, for $t^{\mathbf{Gl}(\lambda x^l.p)} = \lambda x^l.t^p$;
(iv) $\mathbf{Gl}(\lambda x^l.p)t^{\mathbf{Gl}(\lambda x^l.p)} = \exists l(\lambda x^l.pt^p)$, for $t^p = t^{\mathbf{Gl}(\lambda x^l.p)}x^l$;
(v) $\mathcal{H}_G = \mathcal{P}_G \mathcal{T}_G^{\mathcal{P}_G}$ modulo $\beta\eta$ -equality.

PROOF. (i), (ii) immediately from the definition of \mathbf{G} ;
(iii), (iv) from (i), (ii);
(v) from (iii) and (iv). ⊢

REMARK 4.5. By (v) in the previous lemma we have $\mathcal{H}_G = \mathcal{P}_G \mathcal{T}_G^{\mathcal{P}_G}$. In B3.2 we defined $\mathcal{O} = \mathcal{P} \mid \mathcal{G}$ whereas now we have $\mathcal{O}_G = \mathcal{H}_G \mid \mathcal{G}_G$. This corresponds with the fact that now we treat derivations $\Gamma \vdash [\varphi]^2 M$ instead of $\Gamma \vdash [\varphi]^1$.

LEMMA 4.6. Let $\mathcal{W} = \mathcal{L}_G, \mathcal{T}_G^l, \mathcal{P}_G, \mathcal{H}_G, \mathcal{G}_G$, or \mathcal{O}_G and let $w \in \mathcal{W}$, $x^{l_1} \in \mathcal{V}_G^{l_1}$, $t^{l_1} \in \mathcal{T}_G^{l_1}$, then

$$w[x^{l_1} := t^{l_1}] \in \mathcal{W},$$

moreover if $\mathcal{W} = \mathcal{L}_G$ then

$$sk(w[x^{l_1} := t^{l_1}]) \equiv sk(w),$$

and hence

$$\mathcal{V}_G^{w[x^{l_1} := t^{l_1}]} \equiv \mathcal{V}_G^w.$$

PROOF. By induction on the structure of w . Instead of x^{l_1} and t^{l_1} we shall write x and t .

CASE $w \in \mathcal{L}_G$.

$w \equiv A_i$. This is trivially ok.

$w \equiv Pt_1^{A_1}$. This follows from the case $w \equiv t_1^{A_1}$.

$w \equiv \mathbf{Gl}_2(\lambda y^{l_2}.l_3)$. Then $w[x := t] \equiv \mathbf{Gl}_2(x := t)(\lambda y^{l_2}.l_3[x := t]) \equiv$
 $\equiv \mathbf{Gl}_2(x := t)(\lambda y^{l_2[x := t]}.l_3[x := t])$
(by the second part of the IH for l_2) and this is in \mathcal{L}_G by
the first part of the IH for l_2 and l_3 . The second part of the
IH for l_2 and l_3 yields $sk(w[x := t]) \equiv sk(w)$.

CASE $w = t^l \in \mathcal{T}_G^l$.

$l \equiv A_1$. Now $w \equiv x_1^{A_1}, a$ or $t_1^{\mathbf{G}l_1(\lambda x_1^{l_1}.A_1)} t_2^{l_1}$. All these cases are easy.

$l \equiv A_2$ or $Pt_1^{A_1}$. Easy.

$l \equiv \mathbf{G}l_2(\lambda y^{l_2}.l_3)$. Now $w \equiv x_1^l, t_1^{\mathbf{G}l_4(\lambda x_1^{l_4}.l)} t_2^{l_4}, \lambda y^{l_2}.t_1^{l_3}, f$ or g . Easy again.

CASE $w \in \mathcal{P}_G$.

$w \equiv Pt_1^{A_1}$. This follows from the case $w \equiv t_1^{A_1}$.

$w \equiv \mathbf{G}l_2(\lambda y^{l_2}.p)$. Then $w[x := t] \equiv \mathbf{G}(l_2[x := t])(\lambda y^{l_2}.p[x := t]) \equiv$
 $\equiv \mathbf{G}(l_2[x := t])(\lambda y^{l_2[x:=t]}.p[x := t]).$

CASES $w \in \mathcal{H}_G, w \in \mathcal{G}_G$. Similarly. \dashv

LEMMA 4.7. Let $cX_1 \dots X_n =_{\beta\eta} M$ for some constant c and some $M \in \mathcal{O}_G$. Then $n \in \{1, 2\}$ and $M \equiv cY_1 \dots Y_n$ with $Y_i =_{\beta\eta} X_i$.

PROOF. By Church-Rosser for $\beta\eta$ -reduction. \dashv

In the definition of \mathcal{G}_G one of the clauses is $A_i \mathcal{T}_G^{A_i}$ where one might expect the more general clause $l \mathcal{T}_G^l$. But $A_i \mathcal{T}_G^{A_i}$ is sufficient as follows from the next lemma.

LEMMA 4.8.

$lt^l \in \overline{\mathcal{O}_G}$ for each $l \in \mathcal{L}_G$.

PROOF. By induction on the structure of l . It is clear if $l = A_1, A_2$ or Pt^{A_1} . So let $l = \mathbf{G}l_1(\lambda x^{l_1}.l_2)$. Then $lt^l = \mathbf{G}l_1(\lambda x^{l_1}.l_2)t^l = \Xi l_1(\mathbf{S}(\lambda x^{l_1}.l_2)t^l) = \Xi l_1(\lambda x^{l_1}.l_2(t^l x^{l_1}))$. Now $t^l \in \mathcal{T}_G^l = \mathcal{T}_G^{\mathbf{G}l_1(\lambda x^{l_1}.l_2)}$ and $x^{l_1} \in \mathcal{T}_G^{l_1}$, hence $t^l x^{l_1} \in \mathcal{T}_G^{l_2}$. So by the induction hypothesis one has $l_2(t^l x^{l_1}) \in \overline{\mathcal{O}_G}$. Hence $\Xi l_1(\lambda x^{l_1}.l_2(t^l x^{l_1})) \in \overline{\mathcal{O}_G}$. \dashv

LEMMA 4.9.

$lV \in \overline{\mathcal{O}_G} \Rightarrow V \in \overline{\mathcal{T}_G^l}$.

PROOF. By induction on the structure of l . It is clear if $l = A_1, A_2$ or Pt^{A_1} . So let $l = \mathbf{G}l_1(\lambda x^{l_1}.l_2)$. Then $lV = \Xi l_1(\lambda x^{l_1}.l_2(Vx^{l_1}))$. So $l_2(Vx^{l_1}) \in \overline{\mathcal{O}_G}$ and hence by the induction hypothesis we have $Vx^{l_1} = t^{l_2} \in \mathcal{T}_G^{l_2}$. So $V = \lambda x^{l_1}.t^{l_2} \in \mathcal{T}_G^l$. \dashv

Now we will prove $\Gamma \vdash M, \Gamma \subseteq \overline{\mathcal{O}_G} \Rightarrow M \in \overline{\mathcal{O}_G}$. The proof is similar to the proof of Proposition B3.10, but without the induction loading. We used that induction loading to derive, in subcase $\Xi_i(a)$, that if $\Gamma \vdash \Xi(\mathbf{K}p)(\lambda x.O)$ then $x \notin \text{FV}(O)$. But now we have $\Gamma \vdash \Xi(p)(\lambda x.O)$ where x may occur free in O .

PROPOSITION 4.10. \mathcal{O}_G is an invariant (modulo $\beta\eta$ -equality) for derivations in \mathcal{JG} :

$\Gamma \vdash M, \Gamma \subseteq \overline{\mathcal{O}_G} \Rightarrow M \in \overline{\mathcal{O}_G}$.

PROOF. By induction on the derivation of $\Gamma \vdash M$. We only consider the three specific rules Ξ_e, Ξ_i and G_L . (The two general rules are easy and G_e, G_i are equivalent to Ξ_e, Ξ_i .)

CASE Ξ_e . $\Gamma \vdash M$ is $\Gamma \vdash YV$ as direct consequence of $\Gamma \vdash \Xi XY, \Gamma \vdash XV$.

By the IH one has $\Xi XY \in \overline{\mathcal{O}_G}, XV \in \overline{\mathcal{O}_G}$. From $\Xi XY \in \overline{\mathcal{O}_G}$ it follows that $X = l, Y = \lambda x^{l_1}.O$ where $O \in \mathcal{O}_G$. Now $XV = lV \in \overline{\mathcal{O}_G}$, hence $V = t^l \in \mathcal{T}_G^l$ by Lemma 4.9. So $M = (\lambda x^{l_1}.O)t^l = O[x^l := t^l] \in \overline{\mathcal{O}_G}$ by Lemma 4.6.

CASE Ξ_i . $\Gamma \vdash M$ is $\Gamma \vdash \Xi XY$ as direct consequence of

$$\Gamma \vdash \mathbf{L}X, \Gamma, Xx \vdash Yx \text{ with } x \notin \text{FV}(\Gamma, X, Y).$$

By the IH one has $\mathbf{L}X \in \overline{\mathcal{O}_G}$, hence $X = l \in \mathcal{L}_G$. Now x is any variable, so we may assume that $x = x^l \in \mathcal{V}_G^l$. Then $lx \in \overline{\mathcal{O}_G}$ by Lemma 4.8, hence by the IH we have $Yx \in \overline{\mathcal{O}_G}$. Let $Yx = O \in \overline{\mathcal{O}_G}$. Then $M = \Xi l(\lambda x^l.O) \in \overline{\mathcal{O}_G}$.

CASE G_L . $\Gamma \vdash M$ is $\Gamma \vdash \mathbf{L}(\mathbf{G}XY)$ as direct consequence of

$$\Gamma \vdash \mathbf{L}X, \Gamma, Xx \vdash \mathbf{L}(Yx) \text{ with } x \notin \text{FV}(\Gamma, X, Y).$$

By the IH one has $\mathbf{L}X \in \overline{\mathcal{O}_G}$, hence $X = l \in \mathcal{L}_G$. Again we may assume that $x = x^l \in \mathcal{V}_G^l$. Then $lx \in \overline{\mathcal{O}_G}$, hence by the IH we have $\mathbf{L}(Yx) \in \overline{\mathcal{O}_G}$. So $Yx = l_1 \in \mathcal{L}_G$. We get $\mathbf{G}XY = \mathbf{G}l(\lambda x^l.l_1) \in \overline{\mathcal{L}_G}$. Hence $\mathbf{L}(\mathbf{G}XY) \in \overline{\mathcal{O}_G} \subseteq \overline{\mathcal{O}_G}$. \dashv

The invariant \mathcal{O}_G is more complicated than \mathcal{O} and we cannot prove completeness directly using this invariant, as in in B3.11 for $\mathcal{J}\Xi$ relative to PRED. In fact we will use \mathcal{O}_G in order to show in 4.11-4.20 that in each proof $\Gamma \vdash_{\mathcal{J}\mathbf{G}} M$, where $\Gamma \subseteq \overline{\mathcal{O}_G}$, all cut formulas can be eliminated. Then using another invariant \mathcal{O}_1 , similar to \mathcal{O} we prove in Proposition 4.25 completeness of $\mathcal{J}\mathbf{G}$ for PRED in a way similar to the proof of completeness of $\mathcal{J}\Xi$ for PRED.

Cut elimination. First we define the Ξ -length $L_\Xi(O)$ for $O \in \overline{\mathcal{O}_G}$ (and $L_\Xi(l)$ for $l \in \mathcal{L}_G$) and state some lemma's, without the (trivial) proofs.

DEFINITION 4.11 (Ξ -length L_Ξ).

$$L_\Xi((Pt^{A_1})t^{Pt^{A_1}}) = L_\Xi(\mathbf{L}l) = L_\Xi(A_i t^{A_i}) = 0,$$

$$L_\Xi(\Xi l(\lambda x^l.O)) = 1 + L_\Xi(l) + L_\Xi(O),$$

$$L_\Xi(A_i) = L_\Xi(Pt^{A_i}) = 0, \quad L_\Xi(\mathbf{G}l_1(\lambda x^{l_1}.l_2)) = 1 + L_\Xi(l_1) + L_\Xi(l_2).$$

LEMMA 4.12. (i) $X, Y \in \mathcal{L}_G \cup \overline{\mathcal{O}_G}$, $X \rightarrow_{\beta\eta} Y \Rightarrow L_\Xi(X) = L_\Xi(Y)$.

(ii) $X, Y \in \mathcal{L}_G \cup \overline{\mathcal{O}_G}$, $X =_{\beta\eta} Y \Rightarrow L_\Xi(X) = L_\Xi(Y)$.

DEFINITION 4.13. Let $M \in \overline{\mathcal{O}_G}$, $M =_{\beta\eta} O$. Then $L_\Xi(M) = L_\Xi(O)$.

LEMMA 4.14. $L_\Xi(lt^l) = L_\Xi(l)$.

LEMMA 4.15. $X \in \mathcal{L}_G \cup \overline{\mathcal{O}_G}$, $t^l \in \mathcal{T}_G^l \Rightarrow L_\Xi(X[x^l := t^l]) = L_\Xi(X)$.

LEMMA 4.16.

$$\Xi XY \in \overline{\mathcal{O}_G}, XV \in \overline{\mathcal{O}_G} \Rightarrow L_\Xi(XV) < L_\Xi(\Xi XY) \ \& \ L_\Xi(YV) < L_\Xi(\Xi XY).$$

PROOF. $\Xi XY = \Xi l(\lambda x^l.O)$ and $V \in \overline{\mathcal{T}_G^l}$. Now use Lemma's 4.14 and 4.15. \dashv

DEFINITION 4.17. A cut elimination is a proof reduction of the following form

$$\frac{\frac{\frac{\boxed{D_1}}{\mathbf{L}X} \quad \frac{\boxed{D_2}}{Yx} \quad \boxed{D_3}}{\Xi XY} \quad XV}{YV} \quad \Longrightarrow \quad \frac{\boxed{D_3}}{XV} \quad \frac{\boxed{N/x} \boxed{D_2}}{YV}$$

ΞXY is called the cut formula.

LEMMA 4.18. *In a proof of $\Gamma \vdash_{\mathcal{F}_G} M$ (or $\Gamma \vdash_{\mathcal{F}_\Xi} M$), where $\Gamma \subseteq \overline{\mathcal{O}_G}$, all cut formulas can be eliminated by the above proof reduction.*

PROOF. By induction on the maximal Ξ -length of cut formulas in the proof of $\Gamma \vdash_{\mathcal{F}_G} M$. Consider a cut in the proof with a cut formula ΞXY of maximal Ξ -length. Eliminate this cut. Now new cut formulas may have been introduced at XV and YV , however by Lemma 4.16 these have shorter Ξ -length. In the same way all other cut formulas of maximal Ξ -length can be eliminated and so by the induction hypothesis all cut formulas can be eliminated. \dashv

REMARK 4.19. The above can easily be generalised to allow $\beta\eta$ -equality steps (Eq-steps) as follows.

$$\begin{array}{c}
 \boxed{D_1} \quad X_x \quad \boxed{D_2} \\
 \text{LX} \quad Y_x \\
 \hline
 \text{Eq} \frac{\Xi XY}{\Xi X'Y'} \quad \boxed{D_3} \\
 \hline
 Y'V
 \end{array}
 \Longrightarrow
 \begin{array}{c}
 \boxed{D_3} \\
 \text{Eq} \frac{X'V}{XV} \\
 \hline
 \boxed{[V/x]D_2} \\
 \hline
 YV \\
 \text{Eq} \frac{YV}{Y'V}
 \end{array}$$

REMARK 4.20. Similarly we can define cut elimination for \mathcal{F}_P as a proof reduction of the following form.

$$\begin{array}{c}
 X \\
 \boxed{D_1} \quad \boxed{D_2} \\
 \text{HX} \quad Y \quad \boxed{D_3} \\
 \hline
 X \supset Y \quad X \\
 \hline
 Y
 \end{array}
 \Longrightarrow
 \begin{array}{c}
 \boxed{D_3} \\
 X \\
 \boxed{D_2} \\
 Y
 \end{array}$$

This is in fact a special case of Definition 4.17. (Substitute $\mathbf{K}X$ for X and $\mathbf{K}Y$ for Y in Definition 4.17.) Also in a proof of $\Gamma \vdash_{\mathcal{F}_P} M$ where $\Gamma \subseteq \overline{\mathcal{O}_G}$ all cut formulas can be eliminated.

Now we define similar to the set \mathcal{O} in B3.2 a set \mathcal{O}_1 such that $N \subseteq \overline{\mathcal{O}_1}$ for terms N of interest occurring in a cut free proof of $\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{F}_G} [\varphi]^2 M$.

DEFINITION 4.21. *Definition of \mathcal{L}_1 .*

$$\mathcal{L}_1 \equiv A_1 \mid A_2 \mid \mathcal{P}_1.$$

Definition of $sk(l)$ and \mathcal{V}_1^l .

$$\begin{aligned} sk(A_i) &\equiv A_i; \\ sk(Pt^{A_1}) &\equiv Px^{A_1} \quad (\text{i.e., } sk(Pt^{A_1}) \text{ is independent of } t^{A_1}); \\ sk(\mathbf{G}l_2(\lambda x^{l_2}.p_1)) &\equiv \mathbf{G}(sk(l_2))(\lambda x^{l_2}.sk(p_1)). \end{aligned}$$

$$\mathcal{V}_1^l \equiv \{x_1^l, x_2^l, \dots\}, \quad x_i^l = x_i^{sk(l)}, \quad x_i^{p_1} \neq x_i^{p_2} \text{ if } sk(p_1) \neq sk(p_2);$$

Definition of \mathcal{T}_1^l .

$$\begin{aligned} \mathcal{T}_1^l &\equiv \mathcal{V}_1^{A_1} \mid a \mid f \mathcal{T}_1^{A_1} \mid g \mathcal{T}_1^{A_1} \mathcal{T}_1^{A_2} && \text{if } l \equiv A_1; \\ \mathcal{T}_1^l &\equiv \mathcal{V}_1^{A_2} && \text{if } l \equiv A_2; \\ \mathcal{T}_1^l &\equiv \mathcal{V}_1^l \mid \mathcal{T}_1^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_1^{l_1} && \text{if } l \equiv Pt^{A_1}; \\ \mathcal{T}_1^l &\equiv \mathcal{V}_1^l \mid \mathcal{T}_1^{\mathbf{G}l_1(\lambda x^{l_1}.l)} \mathcal{T}_1^{l_1} \mid \lambda x^{l_2}. \mathcal{T}_1^{p_1} && \text{if } l \equiv \mathbf{G}l_2(\lambda x^{l_2}.p_1). \end{aligned}$$

Definition of $\mathcal{P}_1, \mathcal{H}_1, \mathcal{E}_1$ and \mathcal{O}_1 .

$$\begin{aligned} \mathcal{P}_1 &\equiv P\mathcal{T}_1^{A_1} \mid \mathbf{G}l(\lambda x^l.\mathcal{P}_1); \\ \mathcal{H}_1 &\equiv (Pt^{A_1})t^{Pt^{A_1}} \mid \exists l(\lambda x^l.\mathcal{H}_1); \\ \mathcal{E}_1 &\equiv \mathbf{L}\mathcal{L}_1 \mid A_i \mathcal{T}_1^{A_i} \mid \exists l(\lambda x^l.\mathcal{E}_1); \\ \mathcal{O}_1 &\equiv \mathcal{H}_1 \mid \mathcal{E}_1. \end{aligned}$$

REMARKS 4.22. (i) Similar to Lemma 4.4(v) we now have $\mathcal{H}_1 = \mathcal{P}_1 \mathcal{T}_1^{\mathcal{P}_1}$.

(ii) If $l \equiv A_i$ in $\mathbf{G}l(\lambda x^l.p_1)$ in the definition of \mathcal{P}_1 , then x^l may occur free in p_1 ; but if $l \equiv p$ then $x^l \notin \text{FV}(p_1)$. So $\mathbf{G}l(\lambda x^l.p_1)$ may be split into $\mathbf{G}A_i(\lambda x^{A_i}.p_1)$ and $\mathbf{G}p(\mathbf{K}p_1)$ and similarly for $\exists l(\lambda x^l.g)$ in the definition of \mathcal{E}_1 .

(iii) Note that $\overline{\mathcal{O}_1} \subseteq \overline{\mathcal{O}_G}$, hence Lemma 4.18 remains valid if $\overline{\mathcal{O}_G}$ is replaced by $\overline{\mathcal{O}_1}$.

Lemma's 4.6–4.9 mutatis mutandis also hold for \mathcal{O}_1 . Moreover lemma's corresponding to Lemma's B3.7–B3.9 hold. Replace $[-]^1$ by $[-]^2$ and in the lemma corresponding to B3.7 take \mathcal{H}_1 instead of \mathcal{P}_1 .

LEMMA 4.23. Let $p, p' \in \mathcal{P}_1$. Then $pM = p'M' \Rightarrow p = p'$.

PROOF. Induction on p . ⊥

The following lemma corresponds to Proposition B3.10.

LEMMA 4.24. Let $\Gamma \subseteq \overline{\mathcal{O}_1}$ and let $\Gamma \vdash_{\mathcal{T}_G} N$ be a cut free proof. Then

(i) If the last applied rule in the proof is not the Ξ_i -rule, nor the \mathbf{G}_L -rule (modulo the $\beta\eta$ -rule), then $N \in \overline{\mathcal{O}_1}$.

(ii) If $N = lt$ with $l \in \mathcal{L}_1, t \in \mathcal{T}_G^l$ then $N \in \overline{\mathcal{O}_1}$.

PROOF. The proof of (i) and (ii) is by simultaneous induction on $\Gamma \vdash N$. The two general cases are easy, so we only consider Cases Ξ_i , for (ii), and Ξ_e .

CASE Ξ_i . $\Gamma \vdash N$ is $\Gamma \vdash lt = \Xi XY$ as direct consequence of $\Gamma \vdash \mathbf{L}X, \Gamma, Xx \vdash Yx$.

Now $lt = \mathbf{G}l_1(\lambda x^{l_1}.p)t = \exists l_1(\lambda x^{l_1}.p(tx^{l_1})) = \Xi XY$. The IH for $\Gamma, l_1 x^{l_1} \vdash p(tx^{l_1})$ yields $p(tx^{l_1}) = O \in \overline{\mathcal{O}_1}$. So $\exists l_1(\lambda x^{l_1}.p(tx^{l_1})) = \exists l_1(\lambda x^{l_1}.O) \in \overline{\mathcal{O}_1}$.

CASE Ξ_e . $\Gamma \vdash N$ is $\Gamma \vdash YV$ as direct consequence of $\Gamma \vdash \Xi XY$, $\Gamma \vdash XV$.

By the induction hypothesis for $\Gamma \vdash \Xi XY$ we have $\Xi XY \in \overline{\mathcal{O}_1}$. So $\Xi XY = \Xi l_1(\lambda x^{l_1}.O)$. The IH for $\Gamma \vdash l_1 V$ yields $l_1 V \in \overline{\mathcal{O}_1}$, hence $V \in \overline{\mathcal{T}_1^{l_1}}$. So $YV = O[x^{l_1} := V] \in \overline{\mathcal{O}_1}$. \dashv

PROPOSITION 4.25 (Completeness of \mathcal{JG} for PRED).

$$\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{JG}} [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

PROOF. The proof resembles very much the proof of Proposition B3.11. Note that $\Gamma_s^{2,+} \subseteq \overline{\mathcal{G}_1}$ and $\Gamma(\Delta, \varphi) \subseteq \overline{\mathcal{G}_1}$. Hence it is sufficient to prove

$$(**) \quad \Gamma_g, [\Delta]^2 \vdash_{\mathcal{JG}} N, \Gamma_g \subseteq \overline{\mathcal{G}_1}, N = [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PRED}} \varphi.$$

Write $\Gamma = \Gamma_g, [\Delta]^2$. Then $\Gamma \subseteq \overline{\mathcal{O}_1}$. The proof of (**) is by induction on the derivation of $\Gamma \vdash_{\mathcal{JG}} N$. We may assume that the derivation is cut free because $\overline{\mathcal{O}_1} \subseteq \overline{\mathcal{O}_G}$.

CASE 1. $\Gamma \vdash N$ because $N \in \Gamma$.

$N = [\varphi]^2 M$, so $N \notin \overline{\mathcal{G}_1}$, hence $N \in [\Delta]^2$. We get from Lemma 4.23 that $[\varphi]^2 = [\psi]^2$ for some $\psi \in \Delta$. So $\varphi = \psi$ and hence $\varphi \in \Delta$. Therefore $\Delta \vdash_{\text{PRED}} \varphi$.

CASE 2. $\Gamma \vdash N$ is a direct consequence of $\Gamma \vdash N'$ and $N = N'$.

Now $N' = N = [\varphi]^2 M$ and by the IH for N' one has $\Delta \vdash_{\text{PRED}} \varphi$.

CASE Ξ_e . $\Gamma \vdash N$ is $\Gamma \vdash YV$ as direct consequence of $\Gamma \vdash \Xi XY$, $\Gamma \vdash XV$.

$\Gamma \vdash N$ is cut free, hence from Lemma 4.24 we get that $\Xi XY \in \overline{\mathcal{O}_1}$. We distinguish 3 subcases.

SUBCASE $\Xi_e(a)$. $X = A_i$, $Y = \lambda x^{A_i}.h$. Now $h = pt^p = [\psi]^2 t^p$ for some $p \in \mathcal{P}_1$, $\psi \in \mathbb{F}_{\text{PRED}}$. We have $XV = A_i V \in \overline{\mathcal{O}_1}$ by Lemma 4.24. Therefore $V = t^{A_i} = [t_{A_i}]^2$. Now $N = [\varphi]^2 M = YV = (\lambda x^{A_i}. [\psi]^2 t^p) [t_{A_i}]^2 = [\psi]^2 [x^{A_i} := [t_{A_i}]^2] t' = [\psi [x^{A_i} := t_{A_i}]]^2 t'$ for some t' . So $[\varphi]^2 \equiv [\psi [x^{A_i} := t_{A_i}]]^2$. Hence $\varphi \equiv \psi [x^{A_i} := t_{A_i}]$. $\Xi XY = \Xi A_i(\lambda x^{A_i}. pt^p) = \mathbf{G}A_i(\lambda x^{A_i}. p) t'$ (for some t') = $[\forall x^{A_i} \psi]^2 t'$. So we have by the IH $\Delta \vdash_{\text{PRED}} \forall x^{A_i} \psi$. Hence $\Delta \vdash_{\text{PRED}} \psi [x^{A_i} := t_{A_i}] \equiv \varphi$.

SUBCASE $\Xi_e(b)$. $X = p$, $Y = \lambda x^p.h$. Now $Y = \lambda x^p. p_2 t^{p_2}$ where $x^p \notin \text{FV}(p_2)$. Then $N = [\varphi]^2 M = YV = p_2 t'$ for some t' . So $[\varphi]^2 = p_2$. Let $p = [\varphi_1]^2$. Then $\Xi XY = \mathbf{G}p(\mathbf{K}p_2) t'' = \mathbf{F}p p_2 t'' = [\varphi_1 \supset \varphi]^2 t''$ for some t'' . So we have by the IH

$$\Delta \vdash_{\text{PRED}} \varphi_1 \supset \varphi.$$

Also $\Gamma \vdash XV = [\varphi_1]^2 V$. So by the IH one has

$$\Delta \vdash_{\text{PRED}} \varphi_1.$$

Therefore it follows by modus ponens that

$$\Delta \vdash_{\text{PRED}} \varphi.$$

SUBCASE $\Xi_e(c)$. $\Xi XY = \Xi l(\lambda x^l.g.)$ This case is not applicable because $YV \neq [\varphi]^2 M$.

CASE Ξ_i . $\Gamma \vdash N$ is $\Gamma \vdash \Xi XY$ as direct consequence of

$$\Gamma \vdash \mathbf{L}X, \Gamma, Xx \vdash Yx \text{ with } x \notin \text{FV}(\Gamma, X, Y).$$

$\exists XY = [\varphi]^2 M$. So $[\varphi]^2 = \mathbf{G}l_1(\lambda x^{l_1}.p_2)$ for some $l_1 \in \mathcal{L}_1$ and $p_2 \in \mathcal{P}_1$, and $\exists XY = \exists l_1(\lambda x^{l_1}.p_2(Mx^{l_1}))$. We consider 2 subcases.

SUBCASE $\Xi_i(a)$. $X = A_i$. Let $p_2 = [\psi]^2$. Then $\varphi = \forall x^{A_i} \psi$. As $\Gamma, Xx^{A_i} \vdash p_2(Mx^{A_i})$ one has $\Delta \vdash_{\text{PRED}} \psi$ by the IH. Now x^{A_i} does not occur in Γ , so

$$\Delta \vdash_{\text{PRED}} \forall x^{A_i} \psi.$$

SUBCASE $\Xi_i(b)$. $X = p_1$. Let $p_1 = [\varphi_1]^2$, $p_2 = [\varphi_2]^2$. Then $\varphi = \varphi_1 \supset \varphi_2$. Now $\Gamma, [\varphi_1]^2 x \vdash [\varphi_2]^2 (Mx)$. So one has by the IH $\Delta, \varphi_1 \vdash_{\text{PRED}} \varphi_2$. Hence

$$\Delta \vdash_{\text{PRED}} \varphi_1 \supset \varphi_2.$$

CASE G_L . $\Gamma \vdash N$ is $\Gamma \vdash \mathbf{L}(\mathbf{G}XYZ)$ as direct consequence of

$$\Gamma \vdash \mathbf{L}X, \Gamma, Xx \vdash \mathbf{L}(Yx) \text{ with } x \notin \text{FV}(\Gamma, X, Y).$$

This case is not applicable because $\mathbf{L}(\mathbf{G}XYZ) \neq [\varphi]^2 M$. ⊥

§5. Completeness of $\mathcal{S}\mathbf{F}$ for PROP. We must show for $\varphi \in \mathbb{F}_{\text{PROP}}$, $\Delta \subseteq \mathbb{F}_{\text{PROP}}$:

$$\forall \text{ closed } r \exists M \in \Lambda[[\Delta]_r^2, \Gamma_r^2(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{F}} [\varphi]_r^2 M] \Rightarrow \Delta \vdash_{\text{PROP}} \varphi.$$

It is sufficient to show

$$\exists M \in \Lambda[[\Delta]_1^2, \Gamma_1^2(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{F}} [\varphi]_1^2 M] \Rightarrow \Delta \vdash_{\text{PROP}} \varphi.$$

We omit **I** in the notation and we prove

$$[\Delta]^2, \Gamma^2(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{F}} [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PROP}} \varphi.$$

The proof is much simpler than the proof of completeness of $\mathcal{S}\mathbf{G}$ for PRED, because there is no need for cut elimination. We define only one invariant \mathcal{O}_2 in 5.1, similar to \mathcal{O} and \mathcal{O}_1 and using this invariant we prove the completeness in 5.2–5.5.

DEFINITION 5.1 (Invariant for derivations in $\mathcal{S}\mathbf{F}$). \mathcal{V}_2 is a set of proposition variables. For every $p \in \mathcal{P}_2$ there is a different set \mathcal{V}_2^p of variables.

Definition of \mathcal{T}_2^p .

$$\begin{aligned} \mathcal{T}_2^p &\equiv \mathcal{V}_2^p \mid \mathcal{T}_2^{\mathbf{F}p_1 p} \mathcal{T}_2^{p_1}, & \text{if } p \in \mathcal{V}_2; \\ \mathcal{T}_2^p &\equiv \mathcal{V}_2^p \mid \mathcal{T}_2^{\mathbf{F}p_1 p} \mathcal{T}_2^{p_1} \mid \lambda x^{p_2} . \mathcal{T}_2^{p_3}, & \text{if } p \equiv \mathbf{F}p_2 p_3. \end{aligned}$$

Definition of $\mathcal{P}_2, \mathcal{H}_2, \mathcal{G}_2$ and \mathcal{O}_2 .

$$\begin{aligned} \mathcal{P}_2 &\equiv \mathcal{V}_2 \mid \mathbf{F}\mathcal{P}_2\mathcal{P}_2; \\ \mathcal{H}_2 &\equiv vt^v (v \in \mathcal{V}_2) \mid \Xi p_1(\lambda x^{p_1} . \mathcal{H}_2); \\ \mathcal{G}_2 &\equiv \mathbf{L}\mathcal{P}_2 \mid \Xi \mathcal{P}_2(\mathbf{K}\mathcal{G}_2); \\ \mathcal{O}_2 &\equiv \mathcal{H}_2 \mid \mathcal{G}_2. \end{aligned}$$

REMARK 5.2. Similarly to Lemma 4.4(v) we have $\mathcal{H}_2 = \mathcal{P}_2 \mathcal{T}_2^{\mathcal{P}_2}$ modulo $\beta\eta$ -equality. Note that in $\Xi p_1(\lambda x^{p_1} . h)$ in the definition of \mathcal{H}_2 we have $h = p_2 t^{p_2}$ where $x^{p_1} \notin \text{FV}(p_2)$.

We have lemma's similar to Lemma's 4.6–4.9, with similar, but easier, proofs. (Now $\mathcal{L}_2 = \mathcal{P}_2$.)

PROPOSITION 5.3. *In $\mathcal{S}\mathbf{F}$ we have*

$$\Gamma \vdash M, \Gamma \subseteq \overline{\mathcal{O}_2} \Rightarrow M \in \overline{\mathcal{O}_2}.$$

PROOF. Similar to the proof of B3.10. Instead of Case G_L we now have Case F_L . \dashv

- LEMMA 5.4. (i) $\mathcal{G}_2 \cap \mathcal{H}_2 = \emptyset$;
 (ii) $\overline{\mathcal{G}_2} \cap \overline{\mathcal{H}_2} = \emptyset$;
 (iii) $[-]^2 : \mathbb{F}_{\text{PROP}} \rightarrow \mathcal{P}_2$ is a bijection.
 (iv) Let $p, p' \in \mathcal{P}_2$. Then $pM = p'M' \Rightarrow p = p'$.

PROOF. By easy inductions. For (ii) we use Church Rosser. \dashv

PROPOSITION 5.5 (Completeness of $\mathcal{S}\mathbf{F}$ for PROP).

$$[\Delta]^2, \Gamma^2(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{F}} [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PROP}} \varphi.$$

PROOF. Similar to the proof of Proposition 4.25 but easier. The subcases corresponding to subcases $\Xi_e(a)$ and $\Xi_i(a)$ do not occur. \dashv

§6. Completeness of $\mathcal{S}\mathbf{G}$ for $\text{PRED}\lambda \rightarrow$. In this section we will show completeness of $\mathcal{S}\mathbf{G}$ over predicate logic extended with higher type functions. In this logic we may quantify over all functions based on \mathbf{A}_1 and \mathbf{A}_2 and also over functions ranging over functions etc. and we can state e.g.,

$$\forall f_1 \in ((\mathbf{A}_1 \rightarrow \mathbf{A}_2) \rightarrow \mathbf{A}_1) \forall f_2 \in (\mathbf{A}_1 \rightarrow \mathbf{A}_2) [\mathbf{P}(f_1 f_2)].$$

DEFINITION 6.1. $\text{PRED}\lambda \rightarrow_0$, a preliminary version of Predicate Calculus with Higher Type Functions, is defined by

(i) *Types of $\text{PRED}\lambda \rightarrow_0$*

$$\mathbb{L}_{\text{PRED}\lambda \rightarrow_0} = \mathbf{A}_1 \mid \mathbf{A}_2 \mid \mathbb{L}_{\text{PRED}\lambda \rightarrow_0} \rightarrow \mathbb{L}_{\text{PRED}\lambda \rightarrow_0}.$$

(ii) *Variables of $\text{PRED}\lambda \rightarrow_0$*

$$\mathbb{V}^l = \{x_1^l, x_2^l, \dots\} \quad \text{for } l \in \mathbb{L}_{\text{PRED}\lambda \rightarrow_0}.$$

(iii) *Terms of $\text{PRED}\lambda \rightarrow_0$*

$$\begin{aligned} \mathbb{T}^l &= \mathbf{a} \mid \mathbb{V}^l \mid \mathbb{T}^{l_1 \rightarrow l} \mathbb{T}^{l_1}, & \text{if } l &= \mathbf{A}_1; \\ \mathbb{T}^l &= \mathbb{V}^l \mid \mathbb{T}^{l_1 \rightarrow l} \mathbb{T}^{l_1}, & \text{if } l &= \mathbf{A}_2; \\ \mathbb{T}^l &= \mathbf{f} \mid \mathbb{V}^l \mid \mathbb{T}^{l_1 \rightarrow l} \mathbb{T}^{l_1}, & \text{if } l &= \mathbf{A}_1 \rightarrow \mathbf{A}_1; \\ \mathbb{T}^l &= \mathbf{g} \mid \mathbb{V}^l \mid \mathbb{T}^{l_1 \rightarrow l} \mathbb{T}^{l_1}, & \text{if } l &= \mathbf{A}_1 \rightarrow (\mathbf{A}_2 \rightarrow \mathbf{A}_1); \\ \mathbb{T}^l &= \mathbb{V}^l \mid \mathbb{T}^{l_1 \rightarrow l} \mathbb{T}^{l_1}, & \text{if } l &\notin \{\mathbf{A}_1, \mathbf{A}_2, \mathbf{A}_1 \rightarrow \mathbf{A}_1, \mathbf{A}_1 \rightarrow (\mathbf{A}_2 \rightarrow \mathbf{A}_1)\}. \end{aligned}$$

(iv) *Well-formed formulas of $\text{PRED}\lambda \rightarrow_0$*

$$\mathbb{F}_{\text{PRED}\lambda \rightarrow_0} = \mathbf{P}\mathbb{T}^{\mathbf{A}_1} \mid \mathbb{F}_{\text{PRED}\lambda \rightarrow_0} \supset \mathbb{F}_{\text{PRED}\lambda \rightarrow_0} \mid (\forall x^l) \mathbb{F}_{\text{PRED}\lambda \rightarrow_0}.$$

(v) *Postulates of $\text{PRED}\lambda \rightarrow_0$*

$$\begin{aligned}
\varphi \in \Gamma &\Rightarrow \Gamma \vdash \varphi; \\
\Gamma \vdash \varphi \supset \psi, \Gamma \vdash \varphi &\Rightarrow \Gamma \vdash \psi; \\
\Gamma, \varphi \vdash \psi &\Rightarrow \Gamma \vdash \varphi \supset \psi; \\
\Gamma \vdash \forall x^1 \varphi, t \in \mathbb{T}^1 &\Rightarrow \Gamma \vdash \varphi[x^1 := t]; \\
\Gamma \vdash \varphi, x^1 \notin \text{FV}(\Gamma) &\Rightarrow \Gamma \vdash \forall x^1 \varphi.
\end{aligned}$$

DEFINITION 6.2. The mappings $[-]^i_r$ and Γ in B2.12 from \mathbb{F}_{PRED} into $\Lambda^s(\Xi, \mathbf{L})$ and illative contexts respectively are extended to mappings from $\mathbb{F}_{\text{PRED}\lambda \rightarrow_0}$ by altering some clauses and adding some clauses in the following way.

First we define $[A_j]^i_r = A_j$ ($j = 1, 2$), $[l_1 \rightarrow l_2]^i_r = \mathbf{F}[l_1]^i_r[l_2]^i_r$. We will denote $[l]^i_r$ by l . Then we define

$$\begin{aligned}
[x^1]^i_r &= x^l, \quad [t_1 t_2]^i_r = [t_1]^i_r[t_2]^i_r, \\
[\forall x^1 \varphi]^1_r &= \Xi l(\lambda x^l. [\varphi]^1_r), \quad [\forall x^1 \varphi]^2_r = \mathbf{G}l(\lambda x^l. [\varphi]^2_r), \\
\Gamma(x^1) &= l x^l, \quad \Gamma(\forall x^1 \varphi) = \Gamma(\varphi) - \{l x^l\}, \quad \Gamma(t_1 t_2) = \Gamma(t_1) \cup \Gamma(t_2), \\
\Gamma_{r,s}^1 &= \langle \mathbf{L}A_1, \mathbf{L}A_2, \mathbf{F}A_1 A_1 f, \mathbf{F}A_1(\mathbf{F}A_2 A_1)g, \mathbf{F}A_1 \mathbf{H}(r \circ P), A_1 a \rangle, \\
\Gamma_{r,s}^2 &= \langle \mathbf{L}A_1, \mathbf{L}A_2, \mathbf{F}A_1 A_1 f, \mathbf{F}A_1(\mathbf{F}A_2 A_1)g, \mathbf{F}A_1 \mathbf{L}(r \circ P), A_1 a \rangle, \\
\Gamma_{r,s}^{i,+} &= \Gamma_{r,s}^i \cup \{l x_1^l \mid l \neq A_1\}, \\
[-]^i_r, \Gamma_s^i &\text{ and } \Gamma_s^{i,+} \text{ are obtained from } [-]^i_r, \Gamma_{r,s}^i \text{ and } \Gamma_{r,s}^{i,+} \text{ by everywhere omitting } r \\
&\text{i.e., by replacing } r \circ P \text{ by } P.
\end{aligned}$$

PROPOSITION 6.3. $\mathcal{S}\mathbf{G}$ is not complete for $\text{PRED}\lambda \rightarrow_0$.

PROOF. Let $\varphi = \forall x_1^{A_1 \rightarrow A_1} \forall x_2^{A_1} P(x_1 x_2) \supset \forall x_2^{A_1} P x_2$. We will show

$$(*) \quad \forall \text{ closed } r \exists M [\Gamma_{r,s}^{2,+}, \Gamma(\varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]^2_r M],$$

$$(**) \quad \not\vdash_{\text{PRED}\lambda \rightarrow_0} \varphi.$$

PROOF OF (*). Let $X_1 = \mathbf{G}(\mathbf{F}A_1 A_1)(\lambda x_1. \mathbf{G}A_1(\lambda x_2. (r \circ P)(x_1 x_2)))$, $Y_1 = \mathbf{G}A_1(\lambda x_2. (r \circ P)x_2)$, $M = \lambda x^{X_1}. x^{X_1} I$ where $I = \lambda x^{A_1}. x^{A_1}$. We will prove (*) by showing $\forall \text{ closed } r [\Gamma_{r,s}^{2,+} \vdash_{\mathcal{S}\mathbf{G}} \mathbf{F}X_1 Y_1 M]$.

Note that the rules G_e and G_i imply the rules F_e and F_i . Let r be a closed term in $\Lambda^s(\Xi, \mathbf{L})$. We have by rule F_i

$$\mathbf{L}A_1 \vdash \mathbf{F}A_1 A_1 I$$

and from this we get by rule G_e (taking $X = \mathbf{F}A_1 A_1$, $Y = \lambda x_1. \mathbf{G}A_1(\lambda x_2. (r \circ P)(x_1 x_2))$, $Z = x (= x^{X_1})$, $V = I$)

$$\mathbf{L}A_1, X_1 x \vdash Y_1(xI).$$

So we have

$$(1) \quad \mathbf{L}A_1, X_1 x \vdash Y_1(Mx).$$

Moreover rule F_e yields

$$\mathbf{L}A_1, \mathbf{F}A_1 A_1 x_1, A_1 x_2 \vdash A_1(x_1 x_2).$$

Hence we get by applying rule F_e once more

$$\mathbf{L}A_1, \mathbf{F}A_1 \mathbf{L}(r \circ P), \mathbf{F}A_1 A_1 x_1, A_1 x_2 \vdash \mathbf{L}((r \circ P)(x_1 x_2))$$

and by rule G_L twice

$$(2) \quad \mathbf{L}A_1, \mathbf{F}A_1 \mathbf{L}(r \circ P) \vdash \mathbf{L}X_1.$$

From (1) and (2) we get by rule F_i

$$\mathbf{L}A_1, \mathbf{F}A_1 \mathbf{L}(r \circ P) \vdash \mathbf{F}X_1 Y_1 M.$$

This proves (*). But $\not\vdash_{\text{PRED}\lambda \rightarrow 0} \varphi$ because $\text{PRED}\lambda \rightarrow 0$ has no identity function in $\mathbb{T}^{\mathbf{F}A_1 A_1}$. \neg

By similar examples one shows the need for other combinators or λ -terms. In fact all of these are needed in $\text{PRED}\lambda \rightarrow 0$ before completeness can be proved.

DEFINITION 6.4 (Predicate Calculus with Higher Type Functions, $\text{PRED}\lambda \rightarrow$). Types and variables are as for $\text{PRED}\lambda \rightarrow 0$.

Terms of $\text{PRED}\lambda \rightarrow$

$$\begin{aligned} \mathbb{T}^1 &= \mathbf{a} \mid \mathbb{V}^1 \mid \mathbb{T}^{1_1 \rightarrow 1} \mathbb{T}^{1_1}, & \text{if } 1 &= \mathbf{A}_1; \\ \mathbb{T}^1 &= \mathbb{V}^1 \mid \mathbb{T}^{1_1 \rightarrow 1} \mathbb{T}^{1_1}, & \text{if } 1 &= \mathbf{A}_2; \\ \mathbb{T}^1 &= \mathbf{f} \mid \mathbb{V}^1 \mid \mathbb{T}^{1_1 \rightarrow 1} \mathbb{T}^{1_1} \mid \lambda x^{\mathbf{A}_1} . \mathbb{T}^{\mathbf{A}_1}, & \text{if } 1 &= \mathbf{A}_1 \rightarrow \mathbf{A}_1; \\ \mathbb{T}^1 &= \mathbf{g} \mid \mathbb{V}^1 \mid \mathbb{T}^{1_1 \rightarrow 1} \mathbb{T}^{1_1} \mid \lambda x^{\mathbf{A}_1} \mathbb{T}^{\mathbf{A}_2 \rightarrow \mathbf{A}_1}, & \text{if } 1 &= \mathbf{A}_1 \rightarrow (\mathbf{A}_2 \rightarrow \mathbf{A}_1); \\ \mathbb{T}^1 &= \mathbb{V}^1 \mid \mathbb{T}^{1_1 \rightarrow 1} \mathbb{T}^{1_1} \mid \lambda x^{1_2} . \mathbb{T}^{1_3}, & \text{if } 1 &= 1_2 \rightarrow 1_3, \\ & & 1 &\notin \{\mathbf{A}_1 \rightarrow \mathbf{A}_1, \mathbf{A}_1 \rightarrow (\mathbf{A}_2 \rightarrow \mathbf{A}_1)\}. \end{aligned}$$

The well-formed formulas of $\text{PRED}\lambda \rightarrow$ are defined as for $\text{PRED}\lambda \rightarrow 0$, but with the altered terms. The postulates of $\text{PRED}\lambda \rightarrow$ are as for $\text{PRED}\lambda \rightarrow 0$, plus

$$\Gamma \vdash \varphi, \quad \varphi =_{\beta\eta} \psi \quad \Rightarrow \quad \Gamma \vdash \psi.$$

REMARK 6.5. Ordinary predicate logic PRED can be expressed by the pure type system (PTS), see [1],

\mathcal{S}	$*^p, *^s, *^f, \square^p, \square^s$
\mathcal{A}	$*^p : \square^p, *^s : \square^s$
\mathcal{R}	$(*^p, *^p), (*^s, *^p), (*^s, \square^p)$ $(*^s, *^s, *^f), (*^s, *^f, *^f)$

The point is that $*^f$ is a sort for function spaces like $\mathbf{A}_1 \rightarrow \mathbf{A}_2$ or $\mathbf{A}_1 \rightarrow (\mathbf{A}_2 \rightarrow \mathbf{A}_2)$, with $\mathbf{A}_1, \mathbf{A}_2 \in *^s$, but not for higher function spaces like $(\mathbf{A}_1 \rightarrow \mathbf{A}_2) \rightarrow \mathbf{A}_2$. The system $\text{PRED}\lambda \rightarrow$ has higher function spaces and moreover it allows quantification over them. $\text{PRED}\lambda \rightarrow$ can be described more simply as the following PTS.

$\text{PRED}\lambda \rightarrow$

\mathcal{S}	$*^p, *^s, \square^p, \square^s$
\mathcal{A}	$*^p : \square^p, *^s : \square^s$
\mathcal{R}	$(*^p, *^p), (*^s, *^p), (*^s, \square^p), (*^s, *^s)$

DEFINITION 6.6. We extend the mappings $[-]_r^i$ and Γ of Definition 6.2 by

$$[\lambda x^{1_1} . \mathbf{t}^{1_2}]_r^i = \lambda x^{1_1} . [\mathbf{t}^{1_2}]_r^i, \quad \Gamma(\lambda x^{1_1} . \mathbf{t}^{1_2}) = \Gamma(\mathbf{t}^{1_2}) - \{1_1 x^{1_1}\}.$$

PROPOSITION 6.7 (Soundness of the interpretations for $\text{PRED}\lambda\rightarrow$). *Let $\Delta \cup \{\varphi\} \subseteq \mathbb{F}_{\text{PRED}\lambda\rightarrow}$, then the following hold for all closed r .*

- (i) $\Delta \vdash_{\text{PRED}\lambda\rightarrow} \varphi \Rightarrow \Gamma_{r,s}^{1,+}, [\Delta]_r^1, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\Xi} [\varphi]_r^1$.
- (ii) $\Delta \vdash_{\text{PRED}\lambda\rightarrow} \varphi \Rightarrow \Gamma_{r,s}^{2,+}, [\Delta]_r^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]_r^2 M$ for some M .

PROOF. We shall not give the proof here. It is similar to the proof of Proposition B2.14 but longer because many more trivial cases have to be considered. \dashv

Now in 6.8–6.12 we shall prove completeness of $\mathcal{S}\mathbf{G}$ for $\text{PRED}\lambda\rightarrow$ under the indirect translation $[-]^2$. (Completeness of $\mathcal{S}\Xi$ for $\text{PRED}\lambda\rightarrow$ under the direct translation $[-]^1$ also holds, but we shall not give the proof here.)

First we define in Definition 6.8 an invariant \mathcal{O}_3 , similar to \mathcal{O} in B3.2 and \mathcal{O}_1 in Definition 4.21. We have $\mathcal{O}_3 \subseteq \overline{\mathcal{O}_G}$, hence Lemma 4.18 yields that in a proof of $\Gamma \vdash_{\mathcal{S}\mathbf{G}} M$ where $\Gamma \subseteq \overline{\mathcal{O}_3}$ all cut formulas can be eliminated. Then the proof of completeness of $\mathcal{S}\mathbf{G}$ for $\text{PRED}\lambda\rightarrow$ is similar to the proof of completeness of $\mathcal{S}\mathbf{G}$ for PRED in 4.22–4.25.

DEFINITION 6.8 (Invariant \mathcal{O}_3 for $\mathcal{S}\mathbf{G}$).

$$\mathcal{L}_3 \equiv A_1 \mid A_2 \mid \mathbf{F}\mathcal{L}_3\mathcal{L}_3;$$

$$\mathcal{Q}_3 \equiv \mathcal{L}_3 \mid \mathcal{P}_3;$$

$$\mathcal{V}_3^l \equiv \{x_1^l, x_2^l, \dots\}, \quad x_i^{l_1} \neq x_i^{l_2} \text{ if } l_1 \neq l_2;$$

$$\mathcal{T}_3^l \equiv a \mid \mathcal{V}_3^l \mid \mathcal{T}_3^{\mathbf{F}l_1l} \mathcal{T}_3^{l_1}, \quad \text{if } l \equiv A_1;$$

$$\mathcal{T}_3^l \equiv \mathcal{V}_3^l \mid \mathcal{T}_3^{\mathbf{F}l_1l} \mathcal{T}_3^{l_1}, \quad \text{if } l \equiv A_2;$$

$$\mathcal{T}_3^l \equiv f \mid \mathcal{V}_3^l \mid \mathcal{T}_3^{\mathbf{F}l_1l} \mathcal{T}_3^{l_1} \mid \lambda x^{A_1}. \mathcal{T}_3^{A_1}, \quad \text{if } l \equiv \mathbf{F}A_1A_1;$$

$$\mathcal{T}_3^l \equiv g \mid \mathcal{V}_3^l \mid \mathcal{T}_3^{\mathbf{F}l_1l} \mathcal{T}_3^{l_1} \mid \lambda x^{A_1}. \mathcal{T}_3^{\mathbf{F}A_2A_1}, \quad \text{if } l \equiv \mathbf{F}A_1(\mathbf{F}A_2A_1);$$

$$\mathcal{T}_3^l \equiv \mathcal{V}_3^l \mid \mathcal{T}_3^{\mathbf{F}l_1l} \mathcal{T}_3^{l_1} \mid \lambda x^{l_2}. \mathcal{T}_3^{l_3}, \quad \text{if } l \equiv \mathbf{F}l_2l_3, l \notin \{\mathbf{F}A_1A_1, \mathbf{F}A_1(\mathbf{F}A_2A_1)\}.$$

$$\mathcal{P}_3 \equiv P\mathcal{T}_3^{A_1} \mid \mathbf{G}q(\lambda x^q. \mathcal{P}_3);$$

$$\mathcal{H}_3 \equiv (Pt^{A_1})t^{Pt^{A_1}} \mid \Xi q(\lambda x^q. \mathcal{H}_3);$$

$$\mathcal{G}_3 \equiv \mathbf{L}\mathcal{Q}_3 \mid A_i \mathcal{T}_3^{A_i} \mid \Xi q(\lambda x^q. \mathcal{G}_3);$$

$$\mathcal{O}_3 \equiv \mathcal{H}_3 \mid \mathcal{G}_3.$$

$$\mathcal{V}_3^p \equiv \{x_1^p, x_2^p, \dots\}, \quad x_i^p = x_i^{sk(p)}, \quad x_i^{p_1} \neq x_i^{p_2} \text{ if } sk(p_1) \neq sk(p_2);$$

$$sk(l) \equiv l;$$

$$sk(Pt^{A_1}) \equiv Px^{A_1} \quad (\text{i.e., } sk(Pt^{A_1}) \text{ is independent of } t^{A_1});$$

$$sk(\mathbf{G}q(\lambda x^q. p)) \equiv \mathbf{G}(sk(q))(\lambda x^q. sk(p));$$

$$\mathcal{T}_3^p \equiv \mathcal{V}_3^p \mid \mathcal{T}_3^{\mathbf{G}q(\lambda x^q. p)} \mathcal{T}_3^q \quad \text{if } p \equiv Pt^{A_1};$$

$$\mathcal{T}_3^p \equiv \mathcal{V}_3^p \mid \mathcal{T}_3^{\mathbf{G}q(\lambda x^q. p)} \mathcal{T}_3^q \mid \lambda x^{q_1}. \mathcal{T}_3^{p_1}, \quad \text{if } p \equiv \mathbf{G}q_1(\lambda x^{q_1}. p_1).$$

REMARKS 6.9. (i) Similar to Lemma 4.4(v) we now have $\mathcal{H}_3 = \mathcal{P}_3 \mathcal{T}_3^{\mathcal{P}_3}$ modulo $\beta\eta$ -equality.

(ii) If $q \equiv l$ in $\mathbf{G}q(\lambda x^q.p_1)$ in the definition of \mathcal{P}_3 , then x^q may occur free in p_1 ; but if $q \equiv p$ then $x^q \notin \text{FV}(p_1)$. So $\mathbf{G}q(\lambda x^q.p_1)$ may be split into $\mathbf{G}l(\lambda x^l.p_1)$ and $\mathbf{G}p(\mathbf{K}p_1)$ and similarly for $\exists q(\lambda x^q.g)$ in the definition of \mathcal{E}_3 .

Lemma's 4.6–4.9 mutatis mutandis also hold for \mathcal{E}_3 . (Replace l by q .) Moreover lemma's corresponding to Lemma's B3.7–B3.9 hold. Replace $[-]^1$ by $[-]^2$ and in the lemma corresponding to B3.7 take \mathcal{H}_3 instead of \mathcal{P}_3 .

LEMMA 6.10. *Let $p, p' \in \mathcal{P}_3$. Then $pM = p'M' \Rightarrow p = p'$.*

PROOF. Induction on p . ⊢

LEMMA 6.11. *Let $\Gamma \subseteq \overline{\mathcal{E}_3}$ and let $\Gamma \vdash_{\mathcal{S}\mathbf{G}} N$ be a cut free proof. Then*

(i) *If the last applied rule in the proof is not the Ξ_i -rule, nor the \mathbf{G}_L -rule (modulo the $\beta\eta$ -rule), then $N \in \mathcal{E}_3$.*

(ii) *If $N = qt$ with $q \in \mathcal{E}_3$, $t \in \mathcal{T}_G^q$ then $N \in \overline{\mathcal{E}_3}$.*

PROOF. Similar to the Proof of Lemma 4.24. ⊢

PROPOSITION 6.12 (Completeness of $\mathcal{S}\mathbf{G}$ for $\text{PRED}\lambda \rightarrow$ relative to $[-]^2$).

$$\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]^2 M \Rightarrow \Delta \vdash_{\text{PRED}\lambda \rightarrow} \varphi.$$

PROOF. We have $\mathcal{E}_3 \subseteq \overline{\mathcal{E}_G}$, hence by Lemma 4.18 we may assume that the proof of $\Gamma_s^{2,+}, [\Delta]^2, \Gamma(\Delta, \varphi) \vdash_{\mathcal{S}\mathbf{G}} [\varphi]^2 M$ is cut free. Then the proof is similar to the proof of completeness of $\mathcal{S}\mathbf{G}$ for PRED in Proposition 4.25. ⊢

REMARK 6.13 (Higher Order Predicate Calculus). Let us define $\text{PRED}\lambda\omega$ as $\text{PRED}\lambda \rightarrow$ but with

$$\mathbb{L}_{\text{PRED}\lambda\omega} = \mathbf{A}_1 \mid \mathbf{A}_2 \mid \mathbf{H} \mid \mathbb{L}_{\text{PRED}\lambda\omega} \rightarrow \mathbb{L}_{\text{PRED}\lambda\omega}.$$

Thus $\text{PRED}\lambda\omega$ allows quantification over all functions, but also over all predicates and propositions. As a PTS the system $\text{PRED}\lambda\omega$ is $\text{PRED}\lambda \rightarrow$ plus $(\Box^p, *^p)$, (\Box^p, \Box^p) . Given an extension of $\Gamma_{r,s}^i$ to include $\vdash \mathbf{LH}$, we would expect to prove the completeness of $\mathcal{S}\mathbf{G}$ over $\text{PRED}\lambda\omega$, but we have not yet succeeded. In particular we have not been able to prove cut elimination for $\mathbf{LH} \in \Gamma_{r,s}^i$, so the methods employed here are not all available.

§7. Conclusions and remarks. In [2] and in this paper we proved soundness and completeness for the direct and indirect interpretations of propositional and predicate calculus into illative systems:

- (i) $\Delta \vdash_{\text{PROP}} \varphi \Leftrightarrow \forall \text{ closed } r[\dots, [\Delta]_r^1 \vdash_{\mathcal{S}\mathbf{P}} [\varphi]_r^1];$
- (ii) $\Delta \vdash_{\text{PRED}} \varphi \Leftrightarrow \forall \text{ closed } r[\dots, [\Delta]_r^1 \vdash_{\mathcal{S}\mathbf{E}} [\varphi]_r^1];$
- (iii) $\Delta \vdash_{\text{PROP}} \varphi \Leftrightarrow \forall \text{ closed } r \exists M[\dots, [\Delta]_r^2 \vdash_{\mathcal{S}\mathbf{F}} [\varphi]_r^2 M];$
- (iv) $\Delta \vdash_{\text{PRED}} \varphi \Leftrightarrow \forall \text{ closed } r \exists M[\dots, [\Delta]_r^2 \vdash_{\mathcal{S}\mathbf{G}} [\varphi]_r^2 M];$

where \dots_i stands for $\Gamma_r^i(\Delta, \varphi)$ in the cases of PROP and for $\Gamma_{r,s}^{i,+}, \Gamma(\Delta, \varphi)$ in the cases of PRED .

REMARK 7.1. The proof of soundness (\Rightarrow) was always simple. Completeness (\Leftarrow) was proved each time by specialising to $r = \mathbf{I}$. This is a very natural choice, but one may wonder if the proofs can be given for other r , especially for $r = \mathbf{K}$. Inspecting the 4 proofs for $r = \mathbf{I}$ in this paper and in [2] one can verify that all these proofs need only minor changes to yield proofs for $r = \mathbf{K}$.

Let us consider as an example the proof of completeness of $\mathcal{J}\mathbf{G}$ for PRED ((iv) \Leftarrow) taking $r = \mathbf{K}$. Each Pt^{A_1} ($t^{A_1} \in \mathcal{T}_G^{A_1}$) in Section 4 must be replaced by $\mathbf{K}(Pt^{A_1})$. (And a resulting $\mathbf{K}(Pt^{A_1})M$ we rewrite Pt^{A_1} again.) Let us denote for the moment the resulting set \mathcal{P}_G by $\mathcal{P}_{G\mathbf{K}}$ and the set \mathcal{P}_G of Section 4 for $r = \mathbf{I}$ by $\mathcal{P}_{G\mathbf{I}}$. Then

$$\mathcal{P}_{G\mathbf{K}} = \mathbf{K}\mathcal{P}_{G\mathbf{I}}.$$

In Definition 4.2 we define now

$$\mathcal{T}_G^l \equiv \Lambda^s(\Xi, \mathbf{L}) \text{ if } l \equiv \mathbf{K}(Pt^{A_1}).$$

As a result then $\mathcal{T}_G^p = \Lambda^s(\Xi, \mathbf{L})$ for each $p \in \mathcal{P}_{G\mathbf{K}}$. These are nearly all changes that are needed to get a proof for $r = \mathbf{K}$ from the proof for $r = \mathbf{I}$ in Section 4.

In another version of this paper, [3], we were not yet able to give completeness proofs of $\mathcal{J}\mathbf{G}$ for PRED and $\mathcal{J}\mathbf{F}$ for PROP ((iv) \Leftarrow and (iii) \Leftarrow) by specialising to $r = \mathbf{I}$. We there gave completeness proofs by taking $r = \mathbf{K}$, in a way different from the method sketched above. Let us consider now the proof of completeness of $\mathcal{J}\mathbf{G}$ for PRED in [3] taking $r = \mathbf{K}$. From

$$[\varphi]_{\mathbf{K} \circ \mathbf{I}}^2 = \mathbf{K}[\varphi]_{\mathbf{I}}^1$$

in Lemma B2.15 we got

$$(*) \quad [\varphi]_{\mathbf{K}}^2 M = [\varphi]_{\mathbf{I}}^1.$$

Moreover in [3] we had a conservativity result

$$(**) \quad \Gamma \vdash_{\mathcal{J}\mathbf{G}} M \Rightarrow \Gamma \vdash_{\mathcal{J}\Xi} M \text{ for 'suitable' } \Gamma \text{ and } M.$$

Now the completeness proof in [3] was as follows

$$\begin{aligned} \Gamma_{\mathbf{K},s}^{2,+}, [\Delta]_{\mathbf{K}}^2, \Gamma(\Delta, \varphi) &\vdash_{\mathcal{J}\mathbf{G}} [\varphi]_{\mathbf{K}}^2 M \Rightarrow \text{(by } *) \\ \Gamma_{\mathbf{I},s}^{1,+}, [\Delta]_{\mathbf{I}}^1, \Gamma(\Delta, \varphi) &\vdash_{\mathcal{J}\mathbf{G}} [\varphi]_{\mathbf{I}}^1 \Rightarrow \text{(by } * *) \\ \Gamma_{\mathbf{I},s}^{1,+}, [\Delta]_{\mathbf{I}}^1, \Gamma(\Delta, \varphi) &\vdash_{\mathcal{J}\Xi} [\varphi]_{\mathbf{I}}^1 \Rightarrow \text{(by Proposition B3.14)} \\ \Delta &\vdash_{\text{PRED}} \varphi. \end{aligned}$$

(To prove this conservativity result we had to show, in a way similar to the proof in the present paper, that the proof of $\Gamma \vdash_{\mathcal{J}\mathbf{G}} M$ could be made cut free.)

Also completeness of $\mathcal{J}\mathbf{F}$ relative to PROP for $[-]_{\mathbf{K}}^2$ followed from completeness of $\mathcal{J}\mathbf{P}$ relative to PROP for $[-]_{\mathbf{I}}^1$ by a conservativity result for $\mathcal{J}\mathbf{F}$ relative to $\mathcal{J}\mathbf{P}$.

We also proved elsewhere completeness of $\mathcal{J}\mathbf{G}$ relative to $\text{PRED}\lambda \rightarrow$ for $[-]_{\mathbf{K}}^2$. Then completeness of $\mathcal{J}\Xi$ relative to $\text{PRED}\lambda \rightarrow$ for $[-]_{\mathbf{I}}^1$ followed because system $\mathcal{J}\mathbf{G}$ is stronger than system $\mathcal{J}\Xi$. That last completeness is not proved in the present paper.

REMARK 7.2. We defined $\mathbf{P}, \mathbf{F}, \mathbf{G}$ in B2.3 in terms of the constant Ξ and in B2.7 we obtained the following result.

The systems $\mathcal{J}\mathbf{P}, \mathcal{J}\Xi, \mathcal{J}\mathbf{F}$ and $\mathcal{J}\mathbf{G}$ are related as follows

$$\begin{array}{ccc}
 \mathcal{S}\mathbf{F} & \longrightarrow & \mathcal{S}\mathbf{G} \\
 \uparrow & & \uparrow \\
 \mathcal{S}\mathbf{P} & \longrightarrow & \mathcal{S}\Xi
 \end{array}$$

where \longrightarrow denotes nondecreasing strength, i.e., $s_1 \longrightarrow s_2$ means that for all Γ, X

$$\Gamma \vdash_{s_1} X \Rightarrow \Gamma \vdash_{s_2} X.$$

Moreover we had conservativity results like

$$\Gamma \vdash_{\mathcal{S}\mathbf{G}} M \Rightarrow \Gamma \vdash_{\mathcal{S}\Xi} M \text{ for 'suitable' } \Gamma \text{ and } M$$

mentioned above. But in the proofs of soundness and completeness in the present paper we did not use these results. So one may wonder if soundness and completeness remain valid if we define \mathbf{P} , \mathbf{F} and \mathbf{G} to be constants. This is indeed the case (only the bases $\Gamma_{r,s}^1$ and $\Gamma_{r,s}^2$ must be rewritten). In the soundness proofs we did not use the fact that \mathbf{P} , \mathbf{F} and \mathbf{G} were defined in terms of Ξ . Also completeness remains valid because the systems with \mathbf{P} , \mathbf{F} and \mathbf{G} constant are less strong than the systems we considered. For example for system $\mathcal{S}\mathbf{F}$ then one does not have the relation $\mathbf{F} =_{\beta\eta} \lambda x y z. \Xi x (y \circ z)$.

REMARK 7.3. In B4.1 we stated that it is possible to work with variants of the systems $\mathcal{S}\mathbf{P}$, $\mathcal{S}\Xi$, $\mathcal{S}\mathbf{F}$ and $\mathcal{S}\mathbf{G}$ based on β -conversion only. This still holds. One may think that in the Proof of Lemma 4.9 (and the proof of Lemma 6.11) the η -axiom is used. This however is not the case, because by Definition 4.2 not only $f t^{A_1} \in \mathcal{S}_G^{A_1}$, but also $f \in \mathcal{S}_G^{\mathbf{F}A_1A_1}$ and similarly $g \in \mathcal{S}_G^{\mathbf{F}A_1(\mathbf{F}A_2A_1)}$.

REFERENCES

- [1] H. BARENDREGT, *Lambda calculi with types*, *Handbook of logic in computer science* (S. Abramski, D. M. Gabbay, and T. S. E. Maibaum, editors), vol. II, Oxford University Press, 1992.
- [2] H. BARENDREGT, M. BUNDER, and W. DEKKERS, *Systems of illative combinatory logic complete for first-order propositional and predicate calculus*, this JOURNAL, vol. 58 (1993), pp. 769–788.
- [3] W. DEKKERS, M. BUNDER, and H. BARENDREGT, *Completeness of two systems of illative combinatory logic for first-order propositional and predicate calculus*, *Archive for Mathematical Logic* (1998), to appear.

FACULTY OF MATHEMATICS AND COMPUTER SCIENCE
CATHOLIC UNIVERSITY
NIJMEGEN, THE NETHERLANDS
E-mail: wil@cs.kun.nl

FACULTY OF INFORMATICS, DEPARTMENT OF MATHEMATICS
UNIVERSITY OF WOLLONGONG
NSW AUSTRALIA
E-mail: martin.bunder@uow.edu.au

FACULTY OF MATHEMATICS AND COMPUTER SCIENCE
CATHOLIC UNIVERSITY
NIJMEGEN, THE NETHERLANDS
E-mail: henk@cs.kun.nl