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## An EPROM programmer for the ET3400 expansion system

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THE UNIVERSITY OF WOLLONGONG

DEPARTMENT OF COMPUTING SCIENCE

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An EPROM programmer has been constructed that can program 2716 type 2K by 8 bit and 2532 type 4K by 8 bit EPROMs. Expansion to 8K by 8 bits EPROMs is possible. The EPROM programmer is used as a peripheral device to the ET3400 Microcomputer Trainer Expansion system.

Data to be programmed may be down line loaded from a host system or read in from another ROM or EPROM. The EPROM programmer software can program an EPROM, verify that programming was correct, read a ROM or EPROM, check for correct erasure and fill an area of memory with 0xFF.

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# **An EPROM programmer for the ET3400 expansion system**

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## **ABSTRACT**

An EPROM programmer has been constructed that can program 2716 type 2K by 8 bit and 2532 type 4K by 8 bit EPROMs. Expansion to 8K by 8 bits EPROMs is possible. The EPROM programmer is used as a peripheral device to the ET3400 Microcomputer Trainer Expansion system.

Data to be programmed may be down line loaded from a host system or read in from another ROM or EPROM. The EPROM programmer software can program an EPROM, verify that programming was correct, read a ROM or EPROM, check for correct erasure and fill an area of memory with 0xFF.

## **1. Introduction**

In many small microcomputers there is a small amount of ROM that contains a monitor program. The rest of the memory is made up of RAM which does not retain its data after power is turned off. Programs must be reloaded after power is reapplied. This is very inconvenient, especially where frequently used software is involved. The solution to this problem is to write the programs into EPROM which will retain its data after power down.

EPROMs are programmed by setting up the address and data and applying a high voltage programming pulse for a set time. Once the data has been programmed in it can only be erased by exposing the EPROM to high intensity ultraviolet light. To facilitate the programming of EPROMs and EPROM programmer has been constructed that is capable of programming the most common types of EPROMs. It was made as a peripheral device for the existing ET3400 microcomputer trainer system, as this is much more flexible than a stand alone device. The ET3400 system is a small teaching system based on the Heathkit ET3400 microcomputer trainer. An expansion bus and card cage has been added enabling various experiment cards to be plugged in.

## **2. Design Considerations**

### **2.1. Pin Compatibility**

Fortunately, as new EPROM types have been developed they have remained fairly pin compatible with the older types. With the exception of a few pins the pinouts of these devices have remained constant. Even the newer 28 pin devices have been designed so that they are compatible with the 24 pin devices.

Mask programmed ROMs also have the same pinouts as EPROMs. This is done so that systems can be developed using easily programmed EPROMs and then mass produced using the much cheaper (in very large quantities) ROMs without any hardware modifications. Thus if the EPROM programmer can read the data from an EPROM it can also read it from a compatible ROM.

It was decided to concentrate solely on the single supply 24 pin EPROM types rather than the older triple supply ones. Single supply EPROMs require a single 5V supply rather than the 5V and +/- 12V supplies required by the triple supply ones. Table 1 gives the

pinouts of single supply 2K by 8 and 4K by 8 24 pin EPROMs and 8K by 8 and 16K by 8 28 pin EPROMs. Note that the 24 pin devices only differ in two pins and the 28 pin devices fit neatly over the top of the 24 pin devices, with a change in only two more pins.

pin # 24 pins	pin # 28 pins	2716 2K * 8	2532 4K * 8	2764 8K * 8	27128 16K * 8
	1			Vpp	Vpp
	2			A12	A12
1	3	A7	A7	A7	A7
2	4	A6	A6	A6	A6
3	5	A5	A5	A5	A5
4	6	A4	A4	A4	A4
5	7	A3	A3	A3	A3
6	8	A2	A2	A2	A2
7	9	A1	A1	A1	A1
8	10	A0	A0	A0	A0
9	11	D0	D0	D0	D0
10	12	D1	D1	D1	D1
11	13	D2	D2	D2	D2
12	14	Gnd	Gnd	Gnd	Gnd
13	15	D3	D3	D3	D3
14	16	D4	D4	D4	D4
15	17	D5	D5	D5	D5
16	18	D6	D6	D6	D6
17	19	D7	D7	D7	D7
18*	20	~E/Prog A11	~CE	~CE	
19	21	A10	A10	A10	A10
20*	22	~G	~E	~OE	~OE
21*	23	Vpp	Vpp	A11	A11
22	24	A9	A9	A9	A9
23	25	A8	A8	A8	A8
24*	26	Vcc	Vcc	N/C	A13
	27			Pgm	Pgm
	28			Vcc	Vcc

Signals marked '~' are active low.

Pins marked \* have different signals on different EPROM types.

**Table 1 EPROM pinouts**

## 2.2. Software Compatibility

All the EPROMs mentioned in table 1 are programmed in the same manner. The programming voltage Vpp is applied and the correct address and data asserted. The control pins ~CE, ~OE, ~G and ~E/prog are set to the correct level, depending on the EPROM type, and left for 50 milliseconds. After this time the data will have been programmed into the specified location. By having a set of variable control bytes that are initialised when the EPROM type is determined the same routine may be used to program any of the above mentioned EPROM types.

### 2.3. Other Design Considerations

No chip should be inserted or removed from a socket while power or logic levels are present. It was decided to include a dual pole switch to control both the supply and programming voltages. The address, data and control buffers are also enabled by this switch.

The programming supply voltage,  $V_{pp}$ , of 25 volts is not available on the ET3400 system. This voltage could either be supplied by an external power supply or by an on board DC to DC converter. The latter option, although more complex, was chosen to make the operation of the EPROM programmer easier.

### 3. Implementation

Figure 1 shows the circuit diagram for the EPROM programmer. It consists of:

- (i) An interface to the ET3400 expansion bus.
- (ii) A set of buffers for the address, data and control lines.
- (iii) The power supply for  $V_{pp}$ .
- (iv) Electronic switching to allow  $V_{pp}$  to be applied under program control.
- (v) A rotary switch to determine EPROM type.
- (vi) A Zero Insertion Force socket to hold the EPROM.

The pinouts of the signals on the expansion bus are shown in brackets beside the signal.

A 74LS42 is used to decode a board select and three address lines to give a single select line for the EPROM programmer. Address line A2 is used as one of the select lines on PIA2 and inverted for use as a select line on PIA1.

The outputs of the PIAs are buffered by the tristate buffers. These buffers are enabled when the EPROM power switch is on. The buffer on the data lines is also bidirectional.

The power supply for  $V_{pp}$  consists of an oscillator (NE555), a pair of current pumps (C2, D1, D2 and C4, D3, D4) and a voltage regulator (Q1). The output of the oscillator has a swing of 12V which is applied to C2 and C4. The other side of C2 follows this voltage, but is constrained by D1 to always be greater than 11.4V. Thus this side swings between 11.4V and 23.4V. D2 will conduct whenever it is forward biased by more than 0.6V, charging C3 to 22.8V. The second current pump adds this voltage to the input to C4, charging C5 to 33.6V. This voltage will drop under load. Q1 will regulate the on C5 down to 25V for use as  $V_{pp}$ . R2 allows for the adjustment of  $V_{pp}$  between 12V and 33.6V.

The programming voltage may be switched to the EPROM under program control. When PB0 of PIA2 is low and the power switch is turned on, Q2 is turned on allowing  $V_{pp}$  into the EPROM. When Q2 is off the  $V_{pp}$  pin of the EPROM is at 5V.

The three position rotary switch is a simple means of changing the address and control lines to suit different EPROM types. The switch has been wired for 2716 and 2532 type EPROMs. The third position is currently unused. The switch is also connected to three inputs on PIA2 to allow the software to determine the EPROM type.

The EPROM power switch switches  $V_{cc}$  and  $V_{pp}$  to the EPROM. It is also used to enable the tristate buffers.  $V_{cc}$  is buffered and fed into PB4 of PIA2 to tell the software if the power is switched on.

Finally three LEDs are connected to PB5 - 7 of PIA2. These LEDs are used to tell whether programming, verifying or reading operations are in progress.

### 3.1. Addressing

When a PIA is normally wired up its internal registers are addressed as follows:

<u>Address</u>	<u>Register</u>
0	Data Register A
1	Control Register A
2	Data Register B
3	Control Register B

This is fine for eight bit data transfers. The addressing of the PIA registers may be modified to enable sixteen bit transfers (such as outputting EPROM addresses) by swapping A0 and A1 on the register select pins. The address map for the PIA then becomes:

<u>Address</u>	<u>Register</u>
0	Data Register A
1	Data Register B
2	Control Register A
3	Control Register B

Sixteen bit loads and stores, such as `ldx` and `stx`, may now be made. Data Register A will be the high order register and data Register B the low order one.

A PIA may have all the bits in a data register independently configured as input or output. Reading from the input pins and writing to the output pins may be done without affecting the other pins even though they all share the same address.

PIA1 is used to output the EPROM address. It has been connected to allow sixteen bit transfers as described above. Data Register A is used to output the high order address bits and Data Register B outputs the low order bits. Only thirteen bits out of the possible sixteen bits are used to output the address. The three high order bits of Data Register A are used as inputs to signify the EPROM type.

Data Register A of PIA2 is used to transfer data to the EPROM when programming and to transfer data from the EPROM when reading, verifying or checking erasure.

Data Register B of PIA2 is used to control the function of the EPROM programmer. Bit 0 controls the programming voltage  $V_{pp}$ . Bits 1 and 2 control the Enable and Gate inputs to the EPROM respectively. Bit 3 controls the direction of transfers through the data buffer. Bit 4 is used to sense whether the EPROM power switch is on. Bits 5, 6 and 7 control the Read Write and Verify LEDs respectively. Figure 2 gives an address map of the PIAs.

### 4. Software

A program has been written in 6800 assembly language to program 2K or 4K EPROMs. The program currently resides in

`/usr/hardware/eprom/4keprom.s`

on system B. A copy of this program is included as an appendix. The following commands are available:

Program	<code>p&lt;ramstart&gt;[,&lt;count&gt;[,&lt;romstart&gt;]]</code>
Verify	<code>v&lt;ramstart&gt;[,&lt;count&gt;[,&lt;romstart&gt;]]</code>
Read	<code>r&lt;ramstart&gt;[,&lt;count&gt;[,&lt;romstart&gt;]]</code>
Erased?	<code>e[&lt;romstart&gt;[,&lt;count&gt;]</code>
Fill	<code>f&lt;ramstart&gt;[,&lt;count&gt;]</code>
Exit	<code>x[&lt;address&gt;]</code>

Arguments in angle brackets, `<>`, are hexadecimal values and arguments in square brackets, `[]`, are optional. The default values for optional arguments are `0x0800` or `0x1000` for the count when using 2K or 4K EPROMs respectively, `0x0000` for the EPROM start address and the reset vector (`0xf800` for the Heathkit trainers) for the exit address.

The program has been written in structured code. The top level is a command interpreter which takes an input line, extracts the command and argument values. The commands are called as separate subroutines. The command subroutines in turn call other subroutines such as 'ready' which tests for EPROM type and power on and 'putline' which writes a line of text to the screen.

#### **4.1. Command Interpreter**

On cold start or errors the command interpreter prints out a welcoming message which includes a list of available commands and required arguments. It then reads a line of text from the keyboard into a buffer. The command character is stripped off and saved. The arguments are then extracted and stored as sixteen bit numbers along with an argument count. The arguments must be valid hexadecimal numbers, separated by commas and terminated by a newline character.

The next step is to load the default values for 2K EPROMs. If 4K EPROMs are being used the count will later be overwritten by the default value for 4K EPROMs. If the optional arguments have been supplied they will overwrite the default values and thus be used instead.

A jump table is used to identify the command and call the appropriate subroutine. When the subroutine returns the program branches back to a warm start and repeats the command interpreter loop. If the command is not found the program prints an error message and branches back to a cold start.

#### **4.2. Program**

This command programs either a 2K or 4K EPROM. The user may specify the address in RAM of the data to be programmed, a count of how many bytes to program and where to put the data in the EPROM. The count and the EPROM start address are optional.

The 'ready' subroutine is called first. It checks that the EPROM power switch is on and determines the type of EPROM from the position of the rotary switch. If a 4K EPROM is to be programmed it changes the default count value. It also initialies two variables, 'pinit' and 'pprog', with information necessary to program the required type.

The 'ports' subroutine is then called. It programs the PIAs for correct data direction and sets some initial values. As this subroutine returns with the data port configured for reading the EPROM, the direction of this port is then reversed so that data may be written to the EPROM.

The arguments required to determine the start of the RAM buffer, the count and the EPROM start address are read in, overwriting the default values. If these arguments are not supplied then the default value will be used.

The actual programming of the EPROM now follows. The initial control value is written out to the control port. The current EPROM address is written out to the Heathkit display to show the progress of the programmer. The Current EPROM address and data are then written out to the EPROM. The control value is changed to enable programming. After a fifty millisecond delay the control value is changed back to the initial value and the location has been programmed. The RAM and EPROM addresses are incremented and the count decremented. The programming loop is repeated until all bytes have been programmed.

The control value is reset to 0xFF and a farewell message is printed out before returning to the main program.

Note that all the command subroutines follow the same general pattern of calling 'ready' and 'ports', and loading the address and count arguments before performing the required task. The subroutines then reset the control value, print a farewell message and return to the main program.

#### 4.3. Verify

This command verifies that the data has been correctly programmed into the EPROM. 'Ports' and 'ready' are called and the addresses and count loaded if supplied. The control port is set to enable reading of the EPROM. The control value is the same for 2K or 4K EPROMs. The data is read one byte at a time and compared with the corresponding byte in RAM. If an error is found, the EPROM address, data and the correct data are printed in an error message. The subroutine then waits for any key to be pressed before continuing. If an 'x' has been pressed the command is aborted. 'Verify' exits in the same manner as 'program' when it successfully completes or is aborted.

#### 4.4. Erased

This command checks that all the required locations in the EPROM have been erased, i. e. set to 0xFF. It works in the same manner as verify but checks each location for 0xFF rather than comparing it with a location in RAM.

#### 4.5. Read

This command reads the contents of an EPROM or ROM into a specified area of RAM. 'Ports' and 'ready' are called and the appropriate arguments loaded in. The control value is set to enable the EPROM or ROM to be read. The control value is the same for both 2K and 4K devices. Each location is read in turn and dumped into the specified area of RAM. The control register is then set to 0xFF, a farewell message printed and the subroutine returns to the main program.

#### 4.6. Fill

This command fills a specified area of RAM with 0xFF. This is useful when programming an EPROM with several data segments. The RAM buffer is filled with 0xFF and the data segments loaded into the appropriate positions in the buffer. The whole EPROM is then programmed. Unused areas of the EPROM will remain set to the erased value of 0xFF and thus may be programmed at a later date.

Since this command does not use the EPROM programmer hardware 'ports' and 'ready' are not called. The required RAM address and count, if supplied, are loaded and a loop executed filling the required area with 0xFF. The default count is 0x800 so that if 4K EPROMs are to be used the command must either specify the count or the command used twice. The command exits by printing a farewell message and returning to the main program.

#### 4.7. Exit

This command allows the user to exit the EPROM programmer. If the exit address is supplied the command prints a message and jumps to that address. The default exit address is the reset vector for the microcomputer being used. It is read out of locations 0xffff and 0xffff, which is the reset vector for both the 6800 and 6809 microprocessor.

#### 4.8. Other Routines

'Ports' is used to set up both PIAs prior to a command being executed. The two address ports are set up as outputs, with the top three bits of the high order address port being set up as inputs. The data port is set up as input. The initial value of the control port is set to 0xFF before it is set to be an output port. This ensures that there is no glitch as the port changes from being an input (default setting on reset) to an output port.

'Ready' checks that the EPROM power switch is on and determines what type of EPROM, 2K or 4K, is being used. It starts by assuming that a 2K EPROM has been selected and sets 'pinit' and 'pprog' to suit. It then sits in a loop waiting until the power switch is on and either a 2K or 4K EPROM has been selected. The third setting for an 8K EPROM is ignored by this program. If a 4K EPROM has been selected 'pinit' and 'pprog' are reinitialised and the default count set to 0x1000.

The terminal I/O subroutines used by this program are already available in the EPROM on the ET3400 expansion system master card (called 6800lib) and the subroutines needed to use the ET3400 display are in the monitor ROM.



## 5. Operation

The following items of hardware are needed to use the EPROM programmer.

ET3400 trainer

Expansion system with separate +5V, +12V and -12V power supply

Master card with at least 4K of RAM (6K for 4K EPROMs)

EPROM programmer card

Downline load the EPROM programmer software from

/usr/hardware/eprom/4keprom.out

on system B. If the data is to be downline loaded then do so at this stage. Use the B(ias) option on dll to load the data in available RAM.

Start the program running at 0x2000. Turn the EPROM power switch off. Select either 2K (2716) or 4K (2532) type using the rotary switch. Insert the EPROM into the Zero Insertion Force Socket with pin 1 to the upper left. Turn the EPROM power switch on. Enter the required command on the terminal keyboard and press return. When an EPROM is to be programmed it should first be checked for erasure. When it has been programmed it should be verified. The erasure command can also be used to single step through the EPROM data to view the contents. It will skip over locations containing 0xFF.

Sample commands:

p2800,100,400	Program 100 hex bytes starting from location 2800 hex in RAM into the EPROM starting at location 400 hex.
p2800	Program all of the EPROM with data starting at location 2800 hex in RAM. The default count and EPROM start address are used.
p2800,400	Program the first 400 hex bytes of the EPROM with data starting at location 2800 hex in RAM.
v2800	Verify the whole EPROM against data starting at location 2800 hex in RAM.
v2800,100,400	Verify that the first programming example worked correctly.
r2800	Read the whole of the EPROM into RAM starting at location 2800 hex.
e	Check the whole EPROM for erasure.
f2800	Fill 2k (default count) of RAM with 0xFF starting at location 2800 hex.
f2800,1000	Fill 4K or RAM with 0xFF starting at location 2800 hex.
x	Exit to the reset vector (i. e. the Heathkit monitor).
xa000	Exit to ET3400 transparent link.

## 6. Future Enhancements

The EPROM programmer in its current state can only handle 24 pin devices. If the 24 pin ZIF socket was replaced by a 28 pin ZIF socket and the third position of the rotary switch used, its capacity would be increased to include the 2764 8K by 8 bit EPROM type. 24 pin devices could still be used by inserting them in the 28 pin socket so that their pins corresponded to the equivalent 28 pin device types, see table 1. The third position of the rotary switch would be used to connect the enable signal to pin 20, output enable to pin 22 and A11 to pin 23. The program voltage, Vpp, would be connected to pin 1, A12 to pin 2, ~Vppon to pin 27 and the supply voltage, Vcc, to pin 28. Since pin 26 is no connect, Vcc for 24 pin devices may remain connected.

The only software changes required are to check for the 8K position of the rotary switch and reprogram pinit, pprog and the default count to suit the 2764.

It is impractical to extend the design to handle 27128 or 27256 type devices as these require additional address lines and more switching around of control signals. It would be better to design a new EPROM programmer to cater for these types.

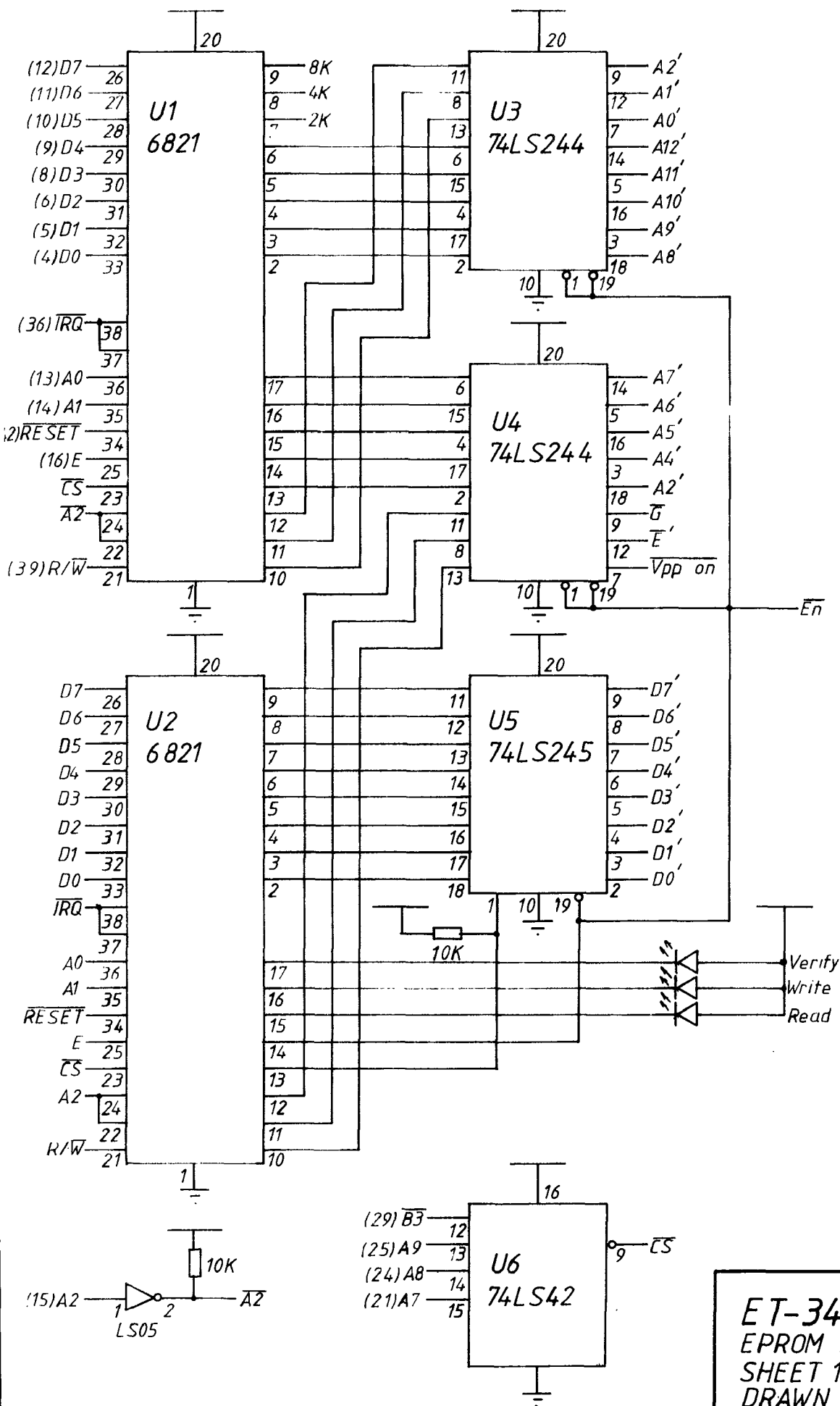


Figure 1a

ET-3400  
 EPROM PROGRAMMER  
 SHEET 1 OF 2  
 DRAWN M.J.M.  
 18/4/1984

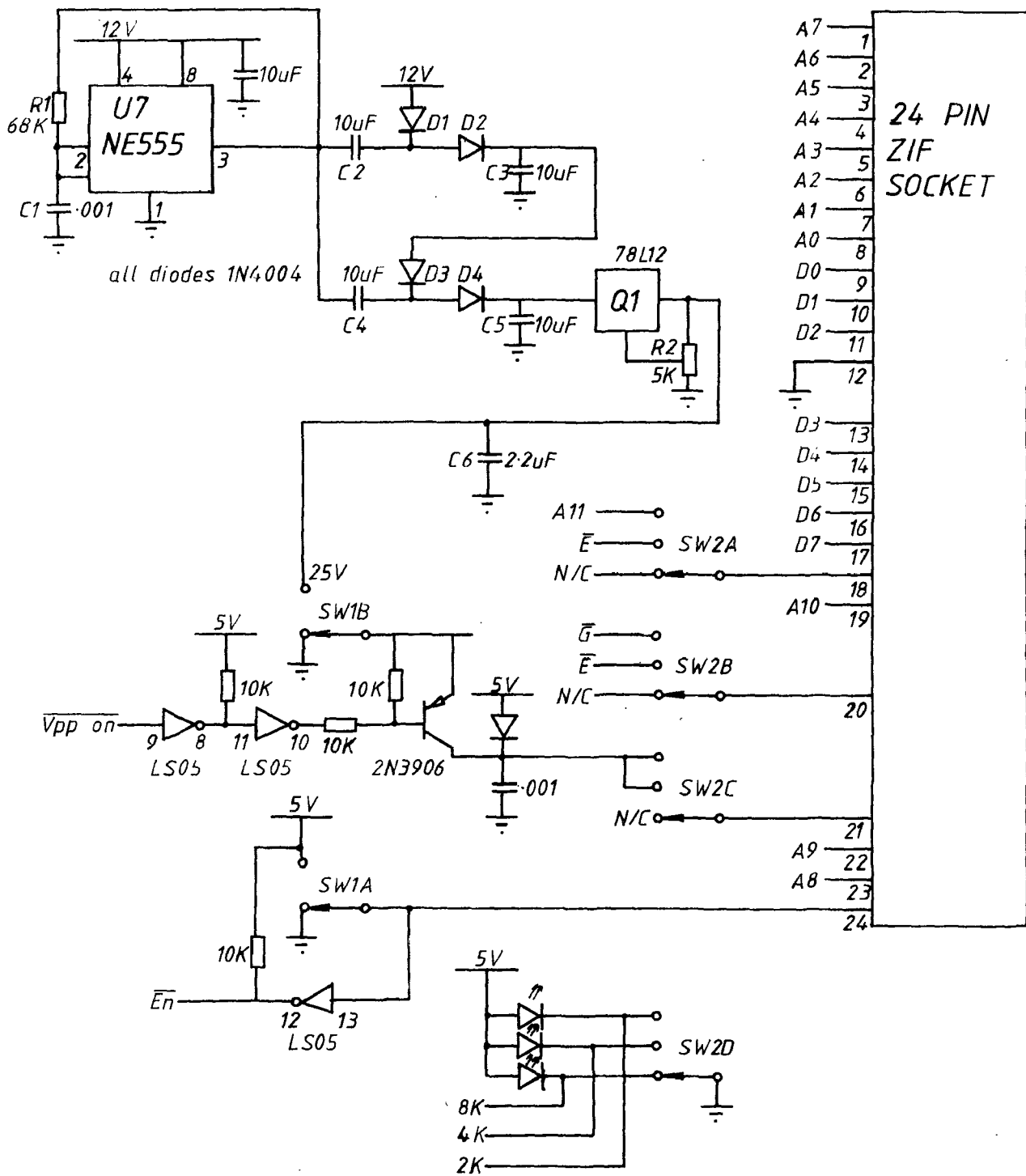


Figure 1b

ET-3400  
 EPROM PROGRAMMER  
 SHEET 2 OF 2  
 DRAWN M.J.M.  
 24/4/1984

Figure 2, Addresses of PIAs, bit usage and data directions.

address port	bit	direction	use	DDR	initial data	
9380	data reg (1A)	7	<--	8K	0	X
		6	<--	4K	0	x
	high order address	5	<--	2K	0	x
		4	-->	A12	1	0
		3	-->	A11	1	0
		2	-->	A10	1	0
		1	-->	A9	1	0
		0	-->	A8	1	0
9381	data reg (2A)	7	-->	A7	1	0
	low order address	6	-->	A6	1	0
		5	-->	A5	1	0
		4	-->	A4	1	0
		3	-->	A3	1	0
		2	-->	A2	1	0
		1	-->	A1	1	0
		0	-->	A0	1	0
9382	control reg (1A)	7				
		6				
		5				
		4	00H to load DDR			
		3	04H to load addresses			
		2				
		1				
		0				
9383	control reg (2A)	7				
		6				
		5				
		4	00H to load DDR			
		3	04H to transfer data			
		2				
		1				
		0				
9384	data reg (1B)	7	<-->	D7	0	1
	EPROM data	6	<-->	D6	0	1
		5	<-->	D5	0	1
		4	<-->	D4	0	1
		3	<-->	D3	0	1
		2	<-->	D2	0	1
		1	<-->	D1	0	1
		0	<-->	D0	0	1

Figure 2 continued.

9385	control reg	7				
	(1B)	6				
		5		DDR = FFH for data write		
		4		DDR = 00H for data read		
		3		00H to load DDR		
		2		04H to transfer data		
		1				
		0				
9386	data reg	7	-->	~verify	1	1
	(2B)	6	-->	~write	1	1
	command/	5	-->	~read	1	1
	status	4	<--	~En	0	x
		3	-->	~drn	1	1
		2	-->	~G	1	1
		1	-->	~E	1	1
		0	-->	~Vppon	1	1
9387	control reg	7				
	(2B)	6				
		5				
		4		00H to load DDR		
		3		04H to transfer commands/status		
		2				
		1				
		0				

note:

Initial data for the command/status register should be loaded before the I/O bits are set to output.

--> means into EPROM

<-- means out of EPROM

<--> means bidirectional data flow

Appendix 1, Software source listing

May 9, 1984

```

; Terminal driven Eprom programmer for use with Heathkit trainers.
; Michael Milway
; 15/8/1983
; ammended 26/4/1984
;
; Commands are:
; Program      p<ramstart>[,<count>[,<romstart>]]
; Verify       v<ramstart>[,<count>[,<romstart>]]
; Read         r<ramstart>[,<count>[,<romstart>]]
; Erased?      e[<romstart>[,<count>]]
; Fill         f<ramstart>[,<count>]
; exit         x[<address>]
;
; equates
dromaddr      equ      0x0000      ;default start address for rom
d2count       equ      0x0800      ;default count
d4count       equ      0x1000      ;default count for 4K
addrhd        equ      0x9380
addrld        equ      0x9381      ;Eprom address registers
addrhc        equ      0x9382
addrlc        equ      0x9383      ;eprom address control registers
datad         equ      0x9384      ;Eprom data register
datac         equ      0x9385      ;Eprom data control register
cntrld        equ      0x9386      ;Programmer control data register
cntrlc        equ      0x9387      ;Programmer control control register
reset         equ      0xffff      ;address of reset vector
redis         equ      0xfcfc      ;reset display routine
outbyt        equ      0xfe20      ;display byte routine
putline       equ      0xa009
getline       equ      0xa00c
wr4           equ      0xa00f
wr2           equ      0xa012
putchar       equ      0xa015
getchar       equ      0xa018
getaddr       equ      0xa02d
tohex         equ      0xa030
toasci        equ      0xa033
tolower       equ      0xa036
ishex         equ      0xa039
ls16          equ      0xa03c
wait          equ      0xa03f
;
;*****
;
;Command
;
;      get command line
;      collect addresses and check for some command errors
;
;      org      0x2000
command
;      ldx      #blurb
;      jsr      putline      ;print out welcoming message
cmd.warm
;      ldx      #cmd.prm
;      jsr      putline      ;the prompt
;      ldx      #buffer
;      jsr      getline      ;get command line

```

```

        ldx    #buffer
        clr    noargs          ;counter for number of arguments
        lda    a,0(x)         ;get command character
        inx
        sta    a,cmmnd
        jsr    getaddr        ;get first argument
        tst    a              ;valid address?
        bne    cmd.1          ;yes
        lda    a,0(x)         ;no, get next character
        jmp    cmd.99
cmd.1   stx    templ
        ldx    addr
        stx    addr1          ;save first address
        ldx    templ
        inc    noargs         ;number of arguments ++
        lda    a,0(x)         ;next char
        inx
        cmp    a,#',-'        ;legal separator
        beq    cmd.2
cmd.2   jmp    cmd.99
        jsr    getaddr        ;yes, next address
        tst    a              ;valid address?
        bne    cmd.3          ;yes
cmd.3   jmp    cmd.err
        stx    templ
        ldx    addr
        stx    addr2          ;second address
        ldx    templ
        inc    noargs
        lda    a,0(x)
        inx
        cmp    a,#',-'        ;legal separator?
        beq    cmd.4          ;yes
cmd.4   jmp    cmd.99
        jsr    getaddr        ;valid address
        tst    a              ;yes
        bne    cmd.5
cmd.5   jmp    cmd.err
        stx    templ
        ldx    addr
        stx    addr3
        ldx    templ
        inc    noargs
        lda    a,0(x)
        inx
cmd.99  cmp    a,#'\n'        ;end of line?
        beq    interp         ;yes, have valid command so interpret it
cmd.err ldx    #errmsg
        jsr    putline        ;output error message
        jmp    command        ;start again
errmsg  dc    "arguments error\n\0"
cmd.prmt dc    "eprom.2-> \0"
;
interp Now have a command and arguments, so interpret it

```



```

ldx      reset           ;default exit
stx      xaddr
ldx      #d2count
stx      count
ldx      #dromaddr
stx      romaddr        ;load default values for 2K
lda      a,cmmid        ;get command
jsr      tolower        ;make lower case
cmp      a,#'p'         ;program?
bne      intr.1         ;no
jsr      program
bra      intr.9
intr.1   cmp      a,#'v'         ;verify?
bne      intr.2
jsr      verify
bra      intr.9
intr.2   cmp      a,#'r'         ;read?
bne      intr.3
jsr      read
bra      intr.9
intr.3   cmp      a,#'e'         ;erased?
bne      intr.4
jsr      erased
bra      intr.9
intr.4   cmp      a,#'f'         ;fill?
bne      intr.5
jsr      fill
bra      intr.9
intr.5   cmp      a,#'x'         ;exit?
bne      intr.6
jmp      exit           ;exit does not return
intr.6   ldx      #cmd.ill        ;must be illegal command
jsr      putline        ;illegal command
jmp      command        ;cold restart
intr.9   jmp      cmd.warm        ;next command
cmd.ill  dc      "illegal command\n\0"
rb       dc      "\nEPROM programmer, version 2\n"
dc      "Program 2K or 4K EPROMs\n"
dc      "Arguments in angle brackets"
dc      " are hex numbers\n"
dc      "Arguments in square"
dc      " brackets are optional\n"
dc      "Commands are:\n"
dc      "Program      p<ramstart>[,<"
dc      "count>[,<romstart>]]\n"
dc      "Verify      v<ramstart>[,<"
dc      "count>[,<romstart>]]\n"
dc      "Read        r<ramstart>[,<"
dc      "count>[,<romstart>]]\n"
dc      "Erased?     e[<romstart>["
dc      ",<count>]]\n"
dc      "Fill FF     f<ramstart>[,"
dc      "<count>]\n"
dc      "exit        x[<addr>]\n"
dc      "type 'x' to abort verify "
dc      "and erased\n"

```

```

dc      "type `return` to continue "
dc      "verify and erased\n"
dc      "Default values are 0800H for "
dc      "count, 0000 for romstart\n"
dc      "and processor reset vector"
dc      " for x\n\0"
;
;      Main Eprom subroutines here
;
title   "Program"
;program an eprom
;inputs:      noargs      number of arguments
;addr1..addr3  initial pointers
;outputs:     none
;calls:       ports, ready, putline
;destroys:    A,B,CC,X,memory pointers
program    jsr      ports      ;set up ports, data = input.
           lda      a,#00
           sta      a,datac
           lda      a,#0xff
           sta      a,datad      ;data = output.
           lda      a,#0x04
           sta      a,datac      ;point to data reg
;check that Eprom is selected and power is on
           jsr      ready
           lda      a,noargs      ;how many arguemants
           bne      psome
           ldx      #toofew
           jsr      putline
           rts
psome      ldx      addr1      ;ramstart
           stx      ramaddr
           dec      a
           beq      pbegin
           ldx      addr2      ;count
           stx      count
           dec      a
           beq      pbegin
           ldx      addr3      ;romaddr
           stx      romaddr
pbegin     lda      a,pinit      ;set up for programming eprom
           sta      a,ctrld
prpt1     jsr      redis
           lda      a,romaddr
           jsr      outbyt
           lda      a,romaddr+1
           jsr      outbyt
           ldx      romaddr      ;get eprom pointer
           stx      addrhd      ;address eprom
           inx
           stx      romaddr      ;next location
           ldx      ramaddr
           lda      a,0x00(x)      ;get data

```

```

        sta      a,datad          ;output to EPROM
        inx
        stx      ramaddr         ;next memory location
        lda      a,pprog         ;program byte
        sta      a,cntrld
        ldx      #6250           ;count for 50msec
        jsr      wait
        lda      a,pinit
        sta      a,cntrld
        ldx      count
        dex
                                ;one less to go
        stx      count
        bne      prptl          ;loop until all positions done
        lda      a,#0xff
        sta      a,cntrld       ;reset program control word
        ldx      #pdone
        jsr      putline        ;say that its done
        rts
pdone   dc      "Program completed\n\0"
        title   "Verify"
        ;verify eprom contents
        ;inputs addr1..addr3,noargs
        ;outputs      none
        ;calls: putline,wr4,ready, ports, wr2, putchar
        ;destroys: all
verify  jsr      ports           ;set up ports, data = input
        ;check selected and power on
        jsr      ready
        lda      a,noargs
        bne      vsome
        ldx      #toofew
        jsr      putline
        rts
vsome   ldx      addr1
        stx      ramaddr
        dec      a
        beq      vbegin
        ldx      addr2
        stx      count
        dec      a
        beq      vbegin
        ldx      addr3
        stx      romaddr        ;load required values
vbegin  lda      a,#0x79
                                ;verify led on
                                ;input data
                                ;output enable on
                                ;chip select on
                                ;Vpp off
vrptl   sta      a,cntrld
        ldx      romaddr        ;get eprom pointer
        stx      addrhd        ;address eprom
        lda      a,datad        ;get eprom data
        ldx      ramaddr

```

```

                                cmp     a,00(x)           ;compare eprom contents with
                                ;memory contents
                                ;no error
                                beq     vgood
                                ldx     #vbad1
                                jsr     putline
                                ldx     romaddr           ;which location?
                                jsr     wr4              ;print it
                                ldx     #vbad2
                                jsr     putline
                                lda     a,datad         ;get bad data
                                jsr     wr2              ;print it
                                ldx     #vbad3
                                jsr     putline
                                ldx     ramaddr
                                lda     a,0(x)         ;get proper data
                                jsr     wr2              ;print it
                                lda     a,#"\n"
                                jsr     putchar
                                jsr     getchar         ;wait for any character to resume
                                cmp     a,#"x"         ;if x then exit
                                beq     vend
vgood                          ldx     ramaddr
                                inx
                                stx     ramaddr
                                ldx     romaddr
                                inx
                                stx     romaddr         ;next location
                                ldx     count
                                dex
                                stx     count
                                bne     vrptl         ;leave loop if all locations
                                ;inspected
vend                            ldx     #vdone
                                jsr     putline         ;print all well message
                                lda     a,#0xff
                                sta     a,cntrl         ;reset programmer control byte
                                rts
vdone                          dc      "Verify completed\n\0"
vbad1                          dc      "Location \0"
vbad2                          dc      " contains \0"
vbad3                          dc      " instead of \0"
                                title "Check 2K EPROM erased"
                                ;read a 2K EPROM from the EPROM programmer
                                ;check that each location = FFH
                                ;inputs:      addr1, addr2, noargs
                                ;outputs:     none
                                ;calls:      ports, ready, putline, wr4, wr2, putchar, getc
                                ;destroys:    all
erased                          jsr     ports          ;set up ports
                                ;check that Eprom is selected and power is on
                                jsr     ready
                                lda     b,noargs       ;how many arguments?
                                beq     ebgn           ;none
                                ldx     addr1         ;start address
                                stx     romaddr

```

```

dec      b
beq      ebgn
ldx      addr2
stx      count      ;how many
ebgn     lda      a,#0x79
                                ;verify led on
                                ;input data
                                ;output enable on
                                ;chip select on
                                ;Vpp off
ewh2     sta      a,cntrld
ldx      romaddr
stx      addrhd     ;address eprom
lda      a,datad    ;get data
cmp      a,#0xff    ;should be FF if erased
beq      egood
ldx      #ebad1
jsr      putline
ldx      romaddr
jsr      wr4
ldx      #ebad2
jsr      putline
lda      a,datad
jsr      wr2        ;write out error message
lda      a,#'\n'
jsr      putchar
jsr      getchar   ;
cmp      a,#'x'    ;x to exit
ebgn     beq      ebye
egood    ldx      romaddr
inx
stx      romaddr   ;next please
ldx      count
dex
stx      count
ebgn     bne      ewh2    ;more?
ebye     ldx      #ebyel
jsr      putline
lda      a,#0xff
sta      a,cntrld  ;turn off read led
rts
ebad1    dc      "Location \0"
ebad2    dc      " contains \0"
ebyel    dc      "Erasure check completed\n\0"
title   "Read 2K Eprom"
;read a 2K EPROM from the EPROM programmer
;inputs: addr1..addr2, noargs
;outputs: none
;calls: ready, ports, putline
;destroys: all
read     jsr      ports      ;set up ports
;check that Eprom is selected and power is on
jsr      ready
lda      a,noargs    ;how many arguments?
bne      rsome      ;at least one
ldx      #toofew

```

```

        jsr    putline
        rts
rsome   ldx    addr1           ;error not enough
        stx    ramaddr
        dec    a
        beq    rbegin
        ldx    addr2
        stx    count
        dec    a
        beq    rbegin
        ldx    addr3
        stx    romaddr
rbegin  lda    a,#0xd9
        ;read led on
        ;input data
        ;output enable on
        ;chip select on
        ;Vpp off
        sta    a,cntrlld
rwhl    ldx    romaddr       ;get address pointer
        stx    addrhd       ;output to Eprom
        inx
        stx    romaddr       ;next
        lda    a,datad       ;get Eprom data
        ldx    ramaddr
        sta    a,0(x)        ;dump to ram
        inx                 ;next address
        stx    ramaddr       ;next dump address
        ldx    count
        dex
        stx    count
        bne    rwhl         ;any more?
        lda    a,#0xff
        sta    a,cntrlld     ;clear control register
        ldx    #rdone
        jsr    putline       ;say read done
        rts
rdone   dc    "Read completed\n\0"
        title "Fill with FF"
        ;Fill ram with 0xFF
        ;inputs: addr1, addr2, noargs
        ;outputs: none
        ;calls: putline
        ;destroys: A, X, CC
fill    lda    a,noargs      ;how many arguments?
        bne    fsome
        ldx    #toofew
        jsr    putline
        rts
fsome   ldx    addr1
        stx    ramaddr
        dec    a
        beq    fbegin

```

```

        ,      ldx      addr2
                stx      count
fbegin
                lda      a,#0xff
fwhl      ldx      ramaddr
                sta      a,0(x)
                inx
                stx      ramaddr
                ldx      count
                dex
                stx      count
                bne      fwhl
                ldx      #fdone
                jsr      putline          ;say fill done
                rts
fdone     dc      "Fill completed\n\0"
exit      ;exit to monitor or user program
          ;inputs:      addr - exit address
          ;outputs:     none
          ;calls:       putline, wr4, putchar, wait
          ;destroys:    all
          lda      a,noargs
          beq      xnone          ;use default exit
          ldx      addr1
          stx      xaddr          ;use user exit address
xnone
          ldx      #exitmsg
          jsr      putline
          ldx      xaddr
          jsr      wr4          ;write out message
          lda      a,#"\n"
          jsr      putchar
          ldx      #6520          ;count for 50 msec
          jsr      wait
          ldx      xaddr
          jmp      0(x)          ;finally exit
exitmsg   dc      "branching to address \0"
ports     title    "misc programmer routines"
          ;set up ports
          ;inputs: none
          ;outputs: none
          ;calls: nothing
          ;destroys: A, X, CC
          lda      a,#0x04
          sta      a,cntrlc          ;point to data part of programmer
                                     ;control register
          lda      a,#0xff
          sta      a,cntrld          ;initial control values all 1's
          lda      a,#00
          sta      a,addr1c
          sta      a,addr1h
          sta      a,datac
          sta      a,cntrlc          ;point to ddr of all ports
          ldx      #0x1fff          ;ddr for address port
          stx      addr1h
          sta      a,datad          ;data port all input

```

```

lda    a,#0xef
sta    a,cntrld      ;1 bit in, 7 bits out
lda    a,#0x04
sta    a,addrhc
sta    a,addrlc
sta    a,datac
sta    a,cntrlc      ;point to data register of all ports
rts
;Ready
;loop until both 2K or 4K selected and power on
;inputs: none
;outputs: none
;calls: nothing
;destroys: A, CC
ready  lda    a,#0xa5      ;assume have 2K eprom
                                ;set up initial value to be used by
                                ;program routine
                                ;write led on, output data, G=1, E=0,
                                ;Vpp off
                                sta    a,pinit
                                lda    a,#0xa6      ;value to be used for programming
                                ;E <-- 1, Vpp <-- on
                                sta    a,pprog
ready1 lda    a,cntrld
and    a,#0x10      ;check power
bne    ready1
lda    a,addrhd      ;get 2k, 4k, 8k switch settings
and    a,#0x20      ;2K?
beq    ready2        ;yes
lda    a,addrhd
and    a,#0x40      ;4K?
bne    ready1        ;neither so wait
;4K so replace pinit and pprog with 4K values
lda    a,#0xa3      ;init value for 4K eprom
                                ;write led on, data output, G=x, E=1
                                ;Vpp off
                                sta    a,pinit
                                lda    a,#0xa0      ;program value
                                ;E <-- 0, Vpp <-- on
                                sta    a,pprog
                                ldx    #d4count      ;default count for 4K
                                stx    count
                                ldx    #r4kmsg
                                jsr    putline
ready2 rts
r4kmsg dc    "4k eprom selected\n\0"
toofew dc    "not enough arguments\n\0"
seg    1
;
;
;
;
addr   equ    0x102      ;return value from getaddr
templ  equ    0x108
addr1  equ    0x10a
addr2  equ    0x10c
addr3  equ    0x10e

```





```

;          4          DDR = 00H for data read
;          3          00H to load DDR
;          2          04H to transfer data
;          1
;          0
;9386  data reg      7      -->      ~verify 1      1
;      (B)          6      -->      ~write  1      1
;      command/    5      -->      ~read   1      1
;      status      4      <--      ~En    0      x
;          3      -->      ~drn   1      1
;          2      -->      ~G     1      1
;          1      -->      ~E     1      1
;          0      -->      ~Vppon 1      1
;9387  control reg  7
;      (B2)        6
;          5
;          4          00H to load DDR
;          3          04H to transfer commands/status
;          2
;          1
;          0
;note:
;      Initial data for the command/status register should be loaded
;before the I/O bits are set to output.
;      --> means into EPROM
;      <-- means out of EPROM
;      <--> means bidirectional data flow
;          end

```